



Product Catalogue 2012



# **CAMDEX** drives



# Company Profile

CAMDEX Machine Works Co., Ltd. is a foreign-invested enterprise, and the first in China to use CNC cam grinding machines to produce hi-speed, precision indexing drives. CAMDEX's strengths include effective management strategies, advanced technology and manufacturing processes, professional equipment, sophisticated product testing and quality assurance, and warm, thoughtful service.



#### Use CAMDEX index drives for:

Auto assembly machines and processing machines; printing machines, pad printing machines, screen printing machines and gold stamping machines; packing machines and vacuum forming machines; automatic testing machines, sorting machines and counting machines;

food processing machines; filling machines; pharmaceutical machines, sealing and capping machines and bottle filling machines; Any application where precision and/or high speed indexing is required, choose CAMDEX.



#### **PROPERTIES**



# Unique Mechanical Features

#### 1. Simplicity and Reliability

A high precision mechanism consisting of only two main moving parts, is capable of providing various types of indexing motions.

#### 2. Inherent Accuracy

During the index drive's dwell (stationary) period, the output shaft (or flange) is accurately fixed in position, eliminating the need for a locking device. CAMDEX standard models are manufactured with an accuracy tolerance of ±30 seconds (1/120 th of a degree). Higher accuracy is available upon request.

#### 3. Motion Curves

For different applications:

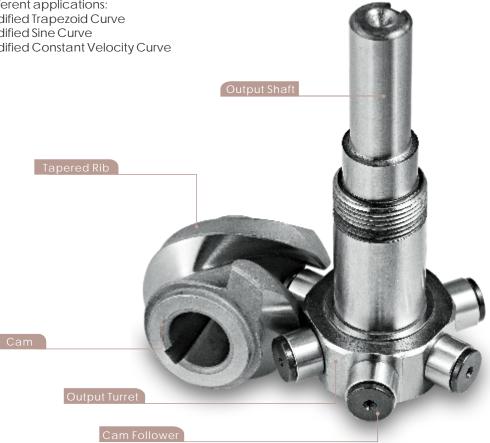
- 1. Modified Trapezoid Curve
- 2. Modified Sine Curve
- 3. Modified Constant Velocity Curve

#### 4. Operation at High Speed

Precision cam followers and tapered ribs are preloaded to avoid gaps and thus capable of providing reliable hispeed operation. The controlled acceleration and deceleration minimizes the impact caused by working loads.

#### 5. Noise and vibration

CAMDEX index drives are designed to operate in any position, and customers will enjoy their quiet running and minimal vibration.



#### STRUCTURAL PRINCIPLE



# Operating Principle and Structure

The structure of an index drive is quite simple. The cam, assembled with the input shaft, Interfaces with the output turret. (Fig. 1) The cam followers are fixed in radials around the output turret and linearly contact the working surface of the tapered cam ribs.

The input shaft rotates, and the cam followers drive the output turret in accordance with the designed motion curve as they roll along the working surfaces of the cam. During the dwelling period, the cam followers do not drive the output turret, though they are still connecting it to the cam. They are locked in a steady and accurate dwell position by the cam. At all times, at least two followers are in continuous contact with the cam, ensuring input shaft rotation is evenly transmitted to the output shaft. This is what provides the smoothness of the indexing motion.



#### Terms and Definitions

#### 1. Roller Gear Cam

A cam fluted into the surface of its barrel type solid body, and fixed to the input shaft.

#### 2. Tapered Rib

The ribs which form the separate cam grooves. The polished sides of the ribs are the cam's working surfaces.

#### 3. Cam Followers

A precision needle roller bearing, capable of working at high speed and heavy load.

#### 4. Output Turret

The extension of the output shaft, driven by the roller gear cam and cam followers.

#### 5. Number of Stops

The number of dwell periods per one revolution of the output shaft.

#### 6 Index Anale

The rotational angle of the input shaft during an index period of the output turret.

#### 7. Dwell Angle

The rotational angle of the input shaft during a dwell period; the sum of dwell angle and index angle is 360°.

#### 8. Number of Rotations

The number of input shaft rotations required to produce one full rotation of the output turret.

#### 9. Steady State Torque

The maximum permissible external torque that may be exerted upon the output shaft by the machine during a dwell period.

#### 10. Dynamic Torque

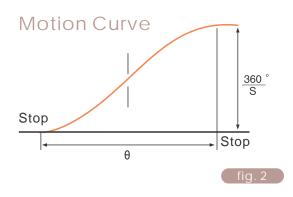
The maximum torque exerted to the output shaft during an index period.

#### STRUCTURAL PRINCIPLE



The motion diagram of an index drive is formed by connecting the start and end of all its motion curves. Indexing motions are designed to make the transition between curves and plateaus as smooth as possible to minimize vibration and noise. Material characteristics are taken into close consideration to produce maximum reliability, lifespan, load and speed ratings. Our indexers are designed to effect the best compromise between all factors. Custom designs can be requested to tilt the balance more towards one area.

The displacement curve shows the relationship between displacements of input shaft (indexing time and angle, etc.) and displacement of output shaft (fig.2). In the diagram, the horizontal axis represents the displacement of input shaft, ' 'while the vertical axis stands for the displacement of output shaft with a given number of stops, 'S'.



# While selecting a cam curve, the values of the following properties must be considered:

Vm The maximum velocity
Am The maximum acceleration

When Vm is greater, there will be a greater force exerted to the cam when it suddenly stops. Therefore, generally a curve with less Vm should be selected, especially when the load is heavier. Vm is also closely related to the cam size. The size of a cam with a less Vm curve is smaller. Note that the value of Vm shall not greater than 1.

When Am is greater, the maximum load allowed is lighter. Therefore, a curve with less Am should be selected in a hi-speed operation, where Am shall not be less than 4.

### STRUCTURAL PRINCIPLE



# There are 3 CAMDEX standard indexing curves:

Modified Trapezoid Curve (MT)

For high speed and light load: fig.3

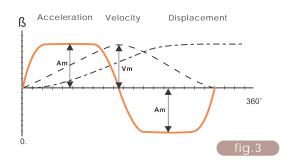
Modified Sine Curve (MS)

For moderate to high speed and moderate load: fig.4

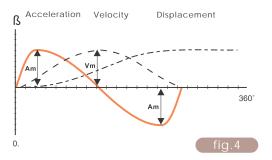
Modified Constant Velocity Curve (MCV50)

For low speed and heavy load: fig.5

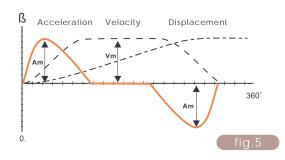
#### Modified Trapezoid Curve (MT)



#### Modified Sine Curve (MS)



### Modified Constant Velocity Curve (MCV50)



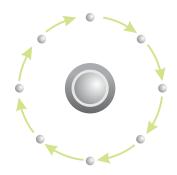
### TYPES OF MOTION



# Different Types of Drives Available

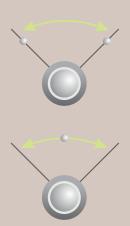
# **Indexing Drives:**

• Convert continuous rotary input into a stop -move - stop motion.



# Oscillating Index Drives:

- Convert continuous rotary input into a left-right (back and forth) motion
- Can also produce a right-center-left-center motion.
- · Are very stable and are suitable for high speed.

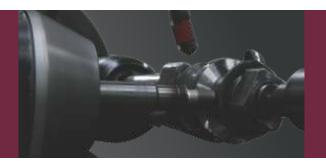


### Roller Drives:

 Roller drive speed reducers are superior to worm gear and other types in several ways, such as zero backlash, significantly higher efficiency and required lower input torque.



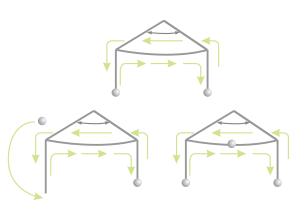
### TYPES OF MOTION



# Different Types of Drives Available

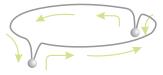
### Oscillating and Conveying Drives:

- Oscillating and conveying drives operate similarly to standard oscillating drives, but incorporate a longitudinal reciprocating movement of the output as well. Different configurations of oscillation and reciprocation may be utilized.
- The output shaft oscillation can be set to stop at the middle point of the rotation. The rotation angle and lifting height can be set accordingly as well.



### Indexing and Conveying Drives:

 Indexing and conveying drives operate similarly to standard indexing drives, but incorporate a longitudinal reciprocating movement of the output as well. The stop can be set at the middle point of the rotation. The rotation angle and lifting height can be set accordingly as well.





# MODEL SELECTION AND CALCULATION



# Symbols and Descriptions

a4	Dwell Coeffient	Lf	Lifespan Factor	Ti	Inertia Torque (kgf.m)
Am	Non-dimensional Acceleration Maximum	Lh	Estimated Lifespan (hr)	Tt	Total Torque needed for Output Shaft (kgf.m)
Amax	Acceleration Maximum(m.s <sup>-2</sup> )	M	Mass (kg)	Tw	Working Torque (kgf.m)
С	Factor of Maximum Acceleration (C>=1)	N	Speed of Cam Shaft (rpm)	Tx	Torque of Camshaft Friction (kgf.m)
D	Rotation Diameter(m)	No	Original Speed of Cam Shaft (rpm)	Ve	Linear Velocity (m.s <sup>-1</sup> )
Е	Energy of Rotator(kgf.m.rpm²)	Р	Travel (m)	Vm	Non-dimensional Velocity Maximum
Eo	Energy of Rotator (kgf.m.rad²)	Pa	Motor Power (kw)	Vmax	Linear Velocity Maximum (m.s <sup>-1</sup> )
Ee	Energy of Linear Moving Object (kgf.m.s <sup>-2</sup> )	Ps	Motor Power Maximum	W	Weight (kg)
F	Centrifugal Force (kgf)	Qm	Cam Shaft Torque Factor Maximum	α	Functional Angle (deg)
G	Weight/Gravity (kgf)	R	Follower Pitch Radius (m)	θ	Indexing Cycle (deg)
GD <sup>2</sup>	Moment of Inertia (kgf.m²)	r	Speed Ratio	μ	Friction Factor
g	Gravity Acceleration (m.s <sup>-2</sup> )	S	Number of Brakes		
1	Polar Moment of Inertia (kgf.m.s²)	Tc	Torque of Camshaft (kgf.m)		
K	Rotation Radius (m)	Td	Torque of Start/Stop (kgf.m)		
Ke	Equivalent Rotation Radius of Output Shaft (m)	Tf	Torque of Friction (kgf.m)		

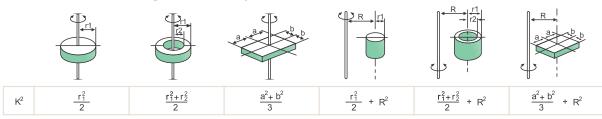
Table 1: Lifespan Factor Lf and Estimated Lifespan Lh

Lifespan (hrs)	Factor	Lifespan (hrs)	Factor	Lifespan (hrs)	Factor	Lifespan (hrs)	Factor
2000 3000 4000 5000 6000 7000	0.617 0.697 0.760 0.812 0.858 0.899	10000 12000 14000 16000 18000 20000	1.00 1.06 1.11 1.15 1.19 1.23	26000 28000 30000 35000 40000 45000	1.33 1.36 1.39 1.46 1.52 1.57	60000 65000 70000 75000 80000 90000	1.71 1.75 1.79 1.83 1.87 1.93
8000 9000	0.935 0.969	22000 24000	1.27 1.30	50000 55000	1.62 1.67	100000	2.00

Table 2: Technical Data of Motion Curves

Motion Curves	(MT)	(MS)	(MCV)	
Symbol	1	2	3	
V m	2.00	1.76	1.28	
Am	+/-4.89	+/-5.53	+/-8.01	
Q m	+/-1.655	+/-0.987	+/-0.715	

Table 3: Reference Drawings of Radius of Gyration



### **SERVICE EXAMPLES**

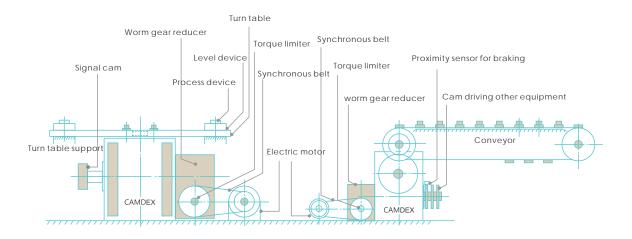


# **Basic Examples**

#### Auto Assembly Machine Series

This mechanism can be used in Auto Assembly Machines; Process Machines; Metal Process Machines; Step Drive Conveyors; FMS Relevant Equipment; Packing Machines; Food Machines; Sorting Machines; Medicine Machines; Printing Machines; Auto Detection Machines; Extrusion Feeding Devices, and indexing machines of other uses.





### Examples using this device

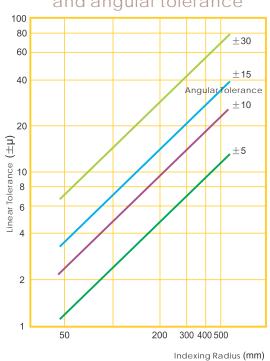


#### **ACHIEVING PRECISION**



# **Indexing Accuracy**

# The relation between linear and angular tolerance



#### Turn Table Size

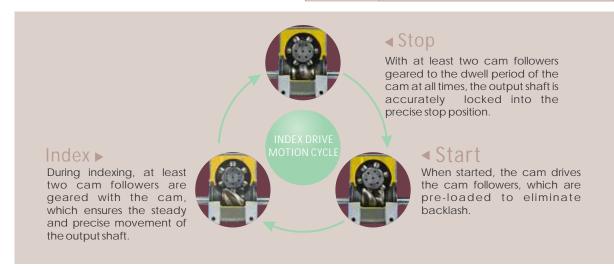
- To mount a turn table on the output shaft, the size of the turn table should be based on the load capacity of the output shaft torque allowed by Torque (Te).
- When high accuracy is required, Torque (Te) should be 2-3 times greater than the output shaft torque allowed; hence, the torque value of the output shaft should be reduced.
- The largest diameter of the turn table should less than 5 times the distance of shaft centers. (fig. 6).

#### **Indexing Accuracy**

 The indexing accuracy is 30 seconds for standard level models, and 15 seconds for precision level models. Please note that the displacement will influence the accuracy when the turn table is mounted on the output shaft.

# The largest diameter allowed of a standard turntable (mm)

Center distance	45	60	70	80	100	110	140	180 250	
Largest diameter	225	300	350	400	500	550	700	900 1250	)





#### LUBRICATION AND MAINTENANCE

### Lubrication and Maintenance

Proper lubrication and maintenance practices are extremely important to preserve the condition of, and maximize the lifespan of index drives. Proper lubrication is effective in reducing heat generation, preventing rust and reducing wear. Failure to observe recommended lubrication and maintenance practices will result in reduced lifespan, inaccuracy due to wear, and premature failure.

The selection of lubricant is also very important. For example, if the lubricant viscosity is too low, operational temperature rise will lower the dynamic viscosity. This will cause more heat, a resulting further degradation of dynamic viscosity and lead to oil film breakdown and rapid failure of the index drive.

#### Lubricating Oil Change

Improperly lubricated internals will lead to rapid wear. This in turn will adversely affect accuracy. Please make sure the index drive is no less than 1/3 full of oil, and observe the lubrication level indicator whenever installation orientation allows. The first lubricating oil change must be performed between 500 to 1000 working hours (2-4 months) of the index drive. Regardless of the working hours, any lubricant will degrade over time, therefore regular lubricating oil changes are necessary.

#### Choice of Lubricants

- Lubrication is an important factor to maintain the accuracy and lifespan of index drives. When choosing lubricants, the conditions of use such as working environment and speed, etc. should be taken into full consideration.
- High quality gear oil should be used, with additives to strengthen oil film, and provide suitable anti corrosion properties also.
- Mixing lubricants from different manufacturers should be avoided.
- Oil viscosity varies due to different speed and device size. Please choose according to the following guidelines.
- Oil viscosity also changes as the environment temperature changes. The working temperature range of index drives is 0-40 celcius. Please refer to the following viscosity-temperature table and please contact us if your application exceeds this standard.

#### Note

- A. Lubricating Oil Change Cycle
  - The first oil change shall be performed in 500-1000 working hours (2-4 months)
  - Afterwards, change oil every 3000 working hours (6 months to 1 year)
- B. When changing oil, ensure the filling hole area is clean to avoid the entry of any contaminants.
- C. Temperature rise will increase the internal pressure, which may cause oil leakage. This should not be ignored. Regularly clean the filling hole and check ventilation hole, oil tubing and oil level, and add lubricant when necessary.



# **LUBRICATION AND MAINTENANCE**

### Lubrication and Maintenance

#### Lubricating Oil Viscosity, Table 4

Input Shaft Speed (rpm)	0~20	20~100	100~200	200~300	300~400	>400	
Viscosity (cSt/40 )	>680	680~460	460~320	320~220	220~150	150~68	

- If input shaft speed is not steady, the viscosity can be determined with the speed of the longest-term operation or the geometric average of the maximum speed (Nmax) and the minimum speed (Nmin)  $\sqrt{\text{Nmax}}$  x (Nmin)
- Choose higher viscosity oil when the correspondent viscosity of the input shaft speed falls in between 2 viscosity ranges.

#### Lubricant Recommended, Table 5

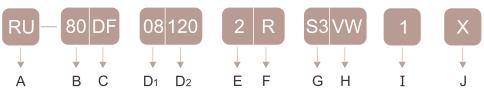
Viscosity	Supplier				
(cSt/40 )	(Caltex)	(Shell)	(Mobil)		
>600	Meropa680	Shell Omala Oil 680	Mobil Gear 636		
680~460	Meropa460	Shell Omala Oil 460	Mobil Gear 633		
460~320	Meropa320	Shell Omala Oil 320	Mobil Gear 632		
320~220	Meropa220	Shell Omala Oil 220	Mobil Gear 630		
220~150	Meropa150	Shell Omala Oil 150	Mobil Gear 629		
150~68	Meropa68	Shell Omala Oil 68	Mobil Gear 626		

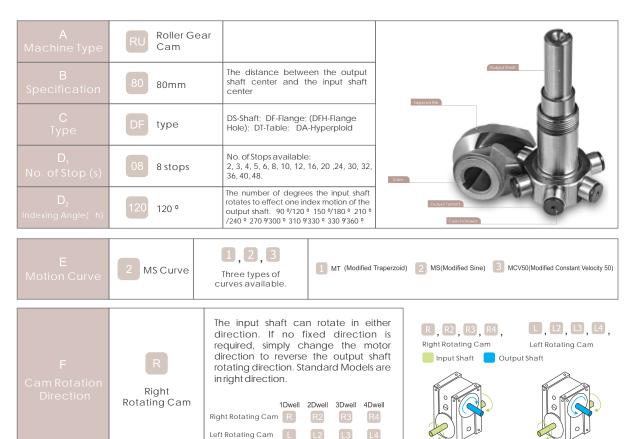


Outstanding Quality, Continuous Improvement

#### **MODEL CODE**

# Model Code Designation:





### Other Types Available

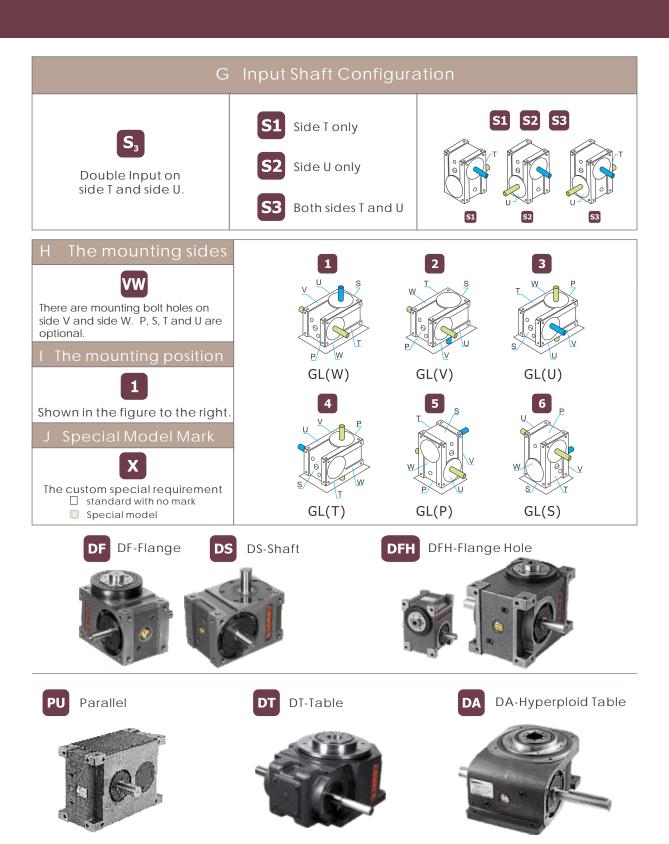
- H. Hollow flange type output shaft (applicable to 45D-250D)
- Hollow output shaft is usually for electric and pneumatic lines. Please specify the hole diameter and the application when placing orders.
- If not specified, the output shaft will be made solid.

Contact our sales staff for assistance in selecting the most appropriate model for you needs.

### Ordering Procedure

- Indexer mounting position: there are six faces available for mounting, V. W. P. S. T. and U. Please specify which face to be mounted on according to the application.
- The model code indicates the positions of the input shaft, the output shaft and the mounting.
- Please specify the model code of the indexing drives needed when placing the order. There are criteria for choosing the correct cam (right rotating or left rotating); as well as choice criteria for the 3 motion curves (MT, MS and MCV50).

# MODEL CODE



# **CAMDEX** drives

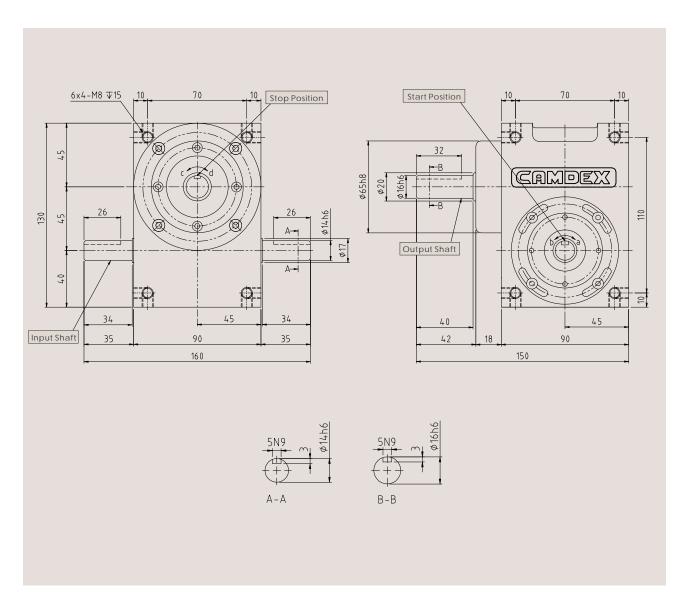


# **DS** Series

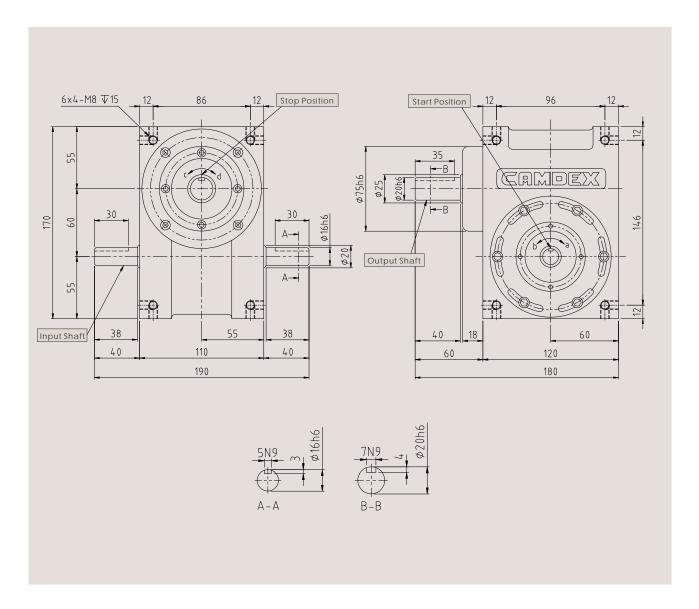
# 45DS / 60DS / 70DS / 80DS / 83DS / 100DS 110DS / 125DS / 140DS / 180DS

#### **Product Features**

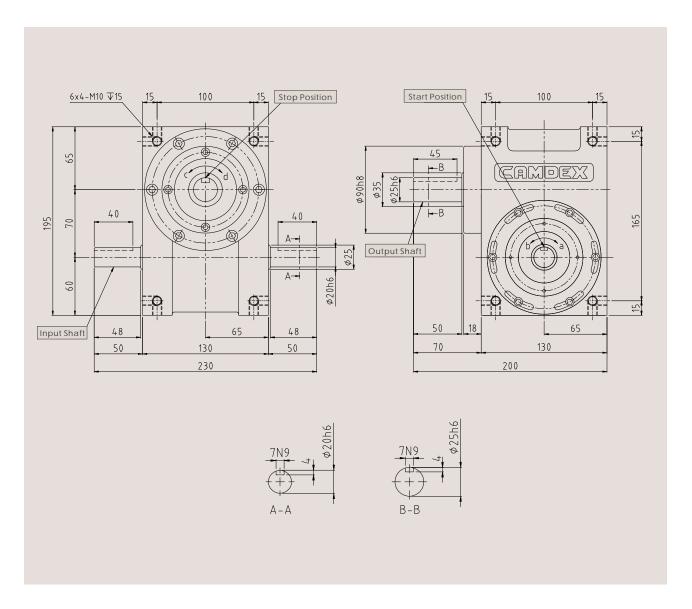
This series of models feature the traditional shaft style. They are sinstalled with some accessories like gears, couplings or clutches. Particular attention should be paid on the diameter tolerances (+0.015 / -0). They are used mostly in belt conveyor drives, gear drives and gap coupling combination drives.



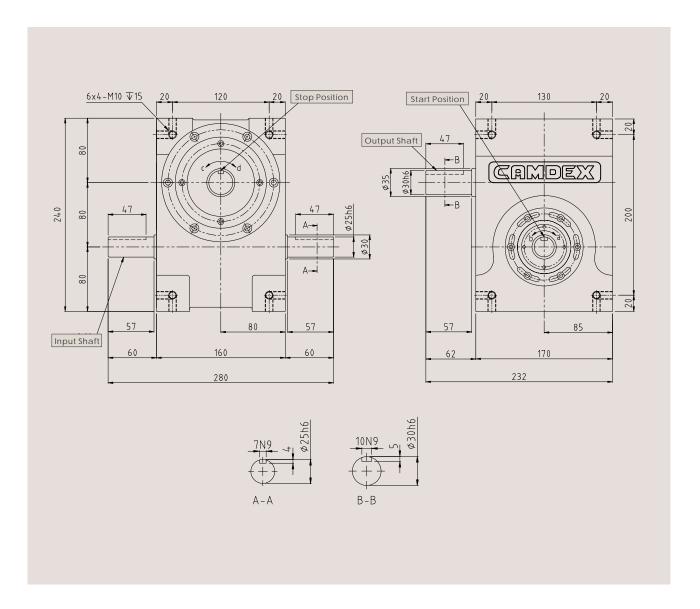
Properties	Symbol	Unit	Value
		1. 6	
Allowable Output shaft radial load	C1	kgf	80
Allowable Output shaft axial load	C2	kgf	72.5
Allowable Output shaft torque	Ts	kgf-m	refer to torque chart
Allowable Input shaft radial load	C3	kgf	85
Max. Input shaft moment of deflection	C4	kgf	75
Max. Input shaft torque	C5	kgf-m	4
Input shaft GD <sup>2</sup>	C6	kgf-m²	3.2x10 <sup>-4</sup>
Positioning indexing accuracy		sec.	$\pm 60$
Weight		kg	7



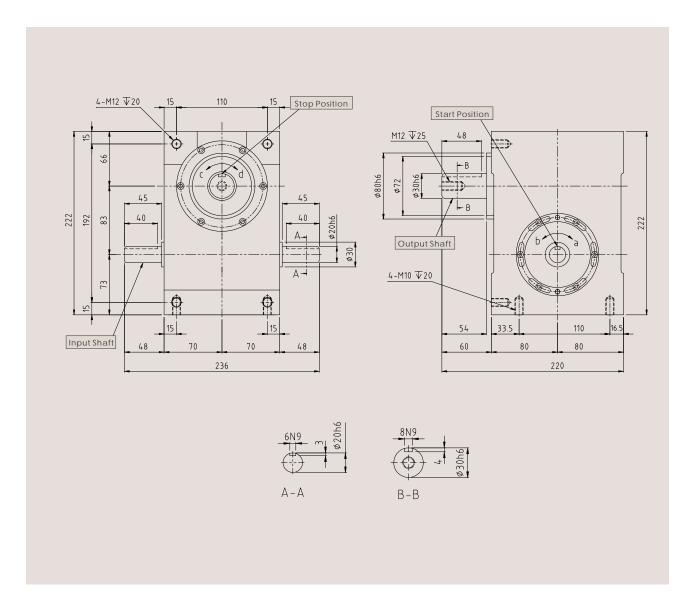
Properties	Symbol		Value
	24	lf	400
Allowable Output shaft radial load	C1	kgf	180
Allowable Output shaft axial load	C2	kgf	150
Allowable Output shaft torque	Ts	kgf-m	refer to torque chart
Allowable Input shaft radial load	C3	kgf	100
Max. Input shaft moment of deflection	C4	kgf	95
Max. Input shaft torque	C5	kgf-m	6
Input shaft GD <sup>2</sup>	C6	kgf-m²	1.9x10 <sup>-3</sup>
Positioning indexing accuracy		sec.	$\pm$ 45
Weight		kg	13



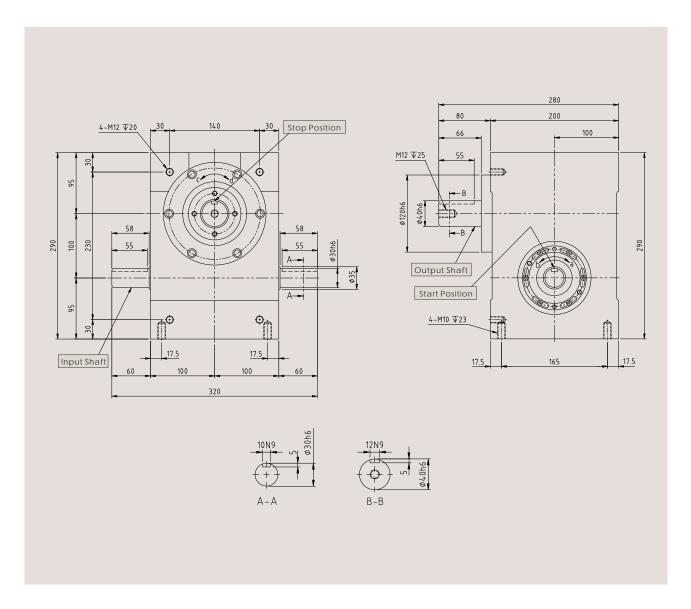
Properties	Symbol	Unit	Value
Allowable Output shaft radial load	C1	kgf	220
Allowable Output shaft axial load	C2	kgf	220
Allowable Output shaft torque	Ts	kgf-m	refer to torque chart
Allowable Input shaft radial load	C3	kgf	150
Max. Input shaft moment of deflection	C4	kgf	110
Max. Input shaft torque	C5	kgf-m	9.5
Input shaft GD <sup>2</sup>	C6	kgf-m²	6x10 <sup>-3</sup>
Positioning indexing accuracy		sec.	±30
Weight		kg	18



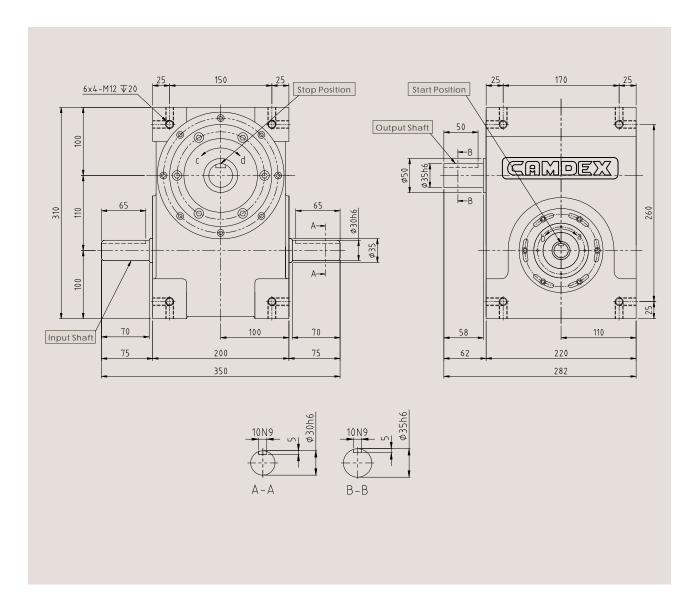
Properties	Symbol		Value
Allowable Output shaft radial load	C1	kgf	220
Allowable Output shaft axial load	C2	kgf	220
Allowable Output shaft torque	Ts	kgf-m	refer to torque chart
Allowable Input shaft radial load	C3	kgf	210
Max. Input shaft moment of deflection	C4	kgf	190
Max. Input shaft torque	C5	kgf-m	18.5
Input shaft GD <sup>2</sup>	C6	kgf-m²	9x10 <sup>-3</sup>
Positioning indexing accuracy		sec.	$\pm 30$
Weight		kg	32



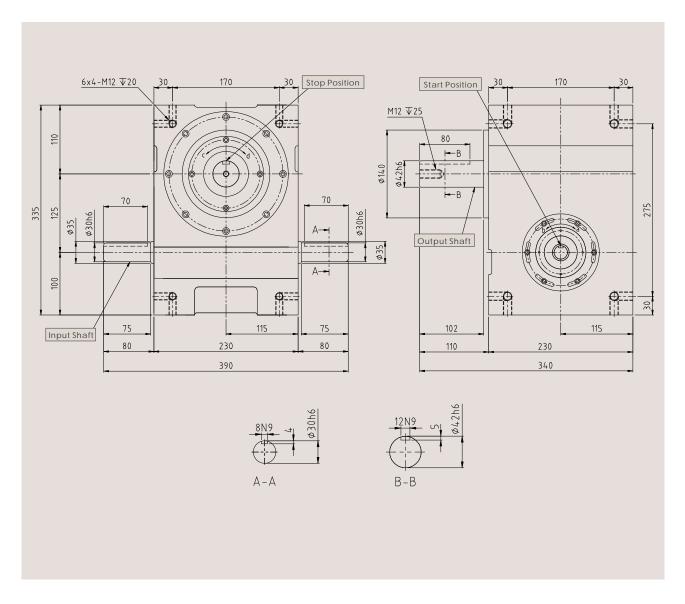
Properties	Symbol	Unit	Value
Allowable Output shaft radial load	C1	kgf	330
Allowable Output shaft axial load	C2	kgf	420
Allowable Output shaft torque	Ts	kgf-m	refer to torque chart
Allowable Input shaft radial load	C3	kgf	350
Max. Input shaft moment of deflection	C4	kgf	260
Max. Input shaft torque	C5	kgf-m	25
Input shaft GD <sup>2</sup>	C6	kgf-m²	9x10 <sup>-3</sup>
Positioning indexing accuracy		sec.	±30
Weight		kg	26.5



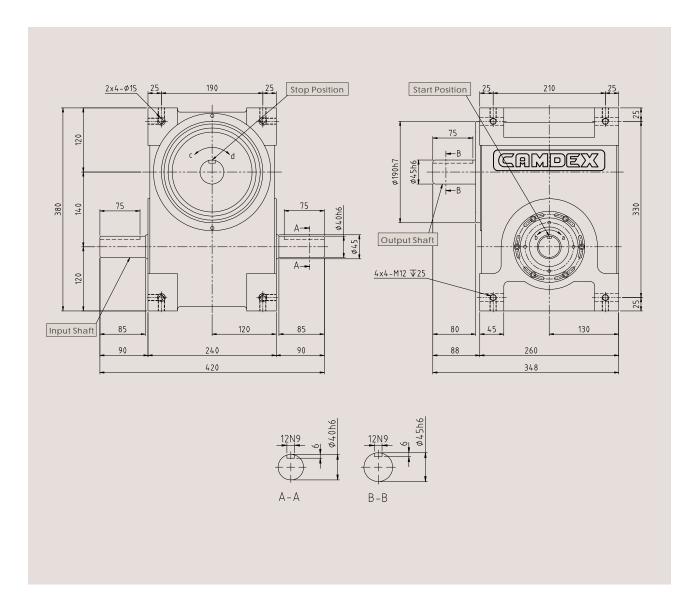
Properties	Symbol		Value
	24	Long	400
Allowable Output shaft radial load	C1	kgf	400
Allowable Output shaft axial load	C2	kgf	450
Allowable Output shaft torque	Ts	kgf-m	refer to torque chart
Allowable Input shaft radial load	C3	kgf	300
Max. Input shaft moment of deflection	C4	kgf	220
Max. Input shaft torque	C5	kgf-m	26
Input shaft GD <sup>2</sup>	C6	kgf-m²	4x10 <sup>-3</sup>
Positioning indexing accuracy		sec.	±30
Weight		kg	50



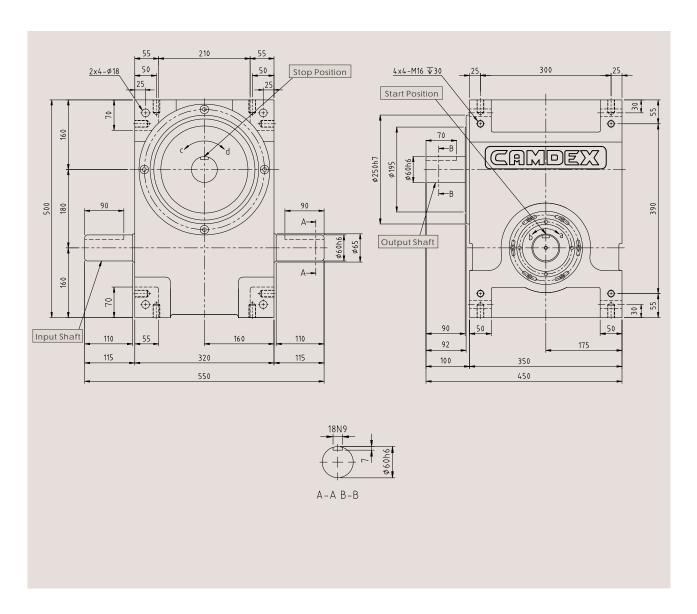
Properties	Symbol	Unit	Value
Allowable Output shaft radial load	C1	kgf	500
Allowable Output shaft axial load	C2	kgf	550
Allowable Output shaft torque	Ts	kgf-m	refer to torque chart
Allowable Input shaft radial load	C3	kgf	360
Max. Input shaft moment of deflection	C4	kgf	290
Max. Input shaft torque	C5	kgf-m	32
Input shaft GD <sup>2</sup>	C6	kgf-m²	2.8x10 <sup>-2</sup>
Positioning indexing accuracy		sec.	±30
Weight		kg	65



Properties	Symbol	Unit	Value
Allowable Output shaft radial load	C1	kgf	610
Allowable Output shaft axial load	C2	kgf	700
Allowable Output shaft torque	Ts	kgf-m	refer to torque chart
Allowable Input shaft radial load	C3	kgf	400
Max. Input shaft moment of deflection	C4	kgf	420
Max. Input shaft torque	C5	kgf-m	51
Input shaft GD <sup>2</sup>	C6	kgf-m²	0.092
Positioning indexing accuracy		sec.	±30
Weight		kg	75



Properties	Symbol	Unit	Value
Allowable Output shaft radial load	C1	kgf	730
Allowable Output shaft axial load	C2	kgf	860
Allowable Output shaft torque	Ts	kgf-m	refer to torque chart
Allowable Input shaft radial load	C3	kgf	440
Max. Input shaft moment of deflection	C4	kgf	560
Max. Input shaft torque	C5	kgf-m	75
Input shaft GD <sup>2</sup>	C6	kgf-m²	0.11
Positioning indexing accuracy		sec.	±30
Weight		kg	90



Properties	Symbol		Value
Allowable Output shaft radial load	C1	kgf	1200
Allowable Output shaft axial load	C2	kgf	1500
Allowable Output shaft torque	Ts	kgf-m	refer to torque chart
Allowable Input shaft radial load	C3	kgf	590
Max. Input shaft moment of deflection	C4	kgf	1045
Max. Input shaft torque	C5	kgf-m	147
Input shaft GD <sup>22</sup>	C6	kgf-m²	0.39
Positioning indexing accuracy		sec.	$\pm 30$
Weight		kg	220

# **CAMDEX** drives



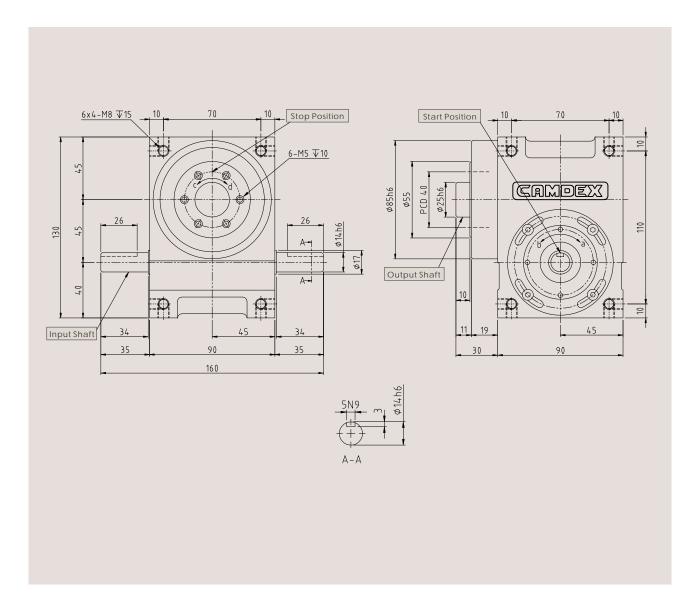
# **DF** Series

# 45DF/60DF/70DF/80DF 110DF/125DF/140DF/180DF

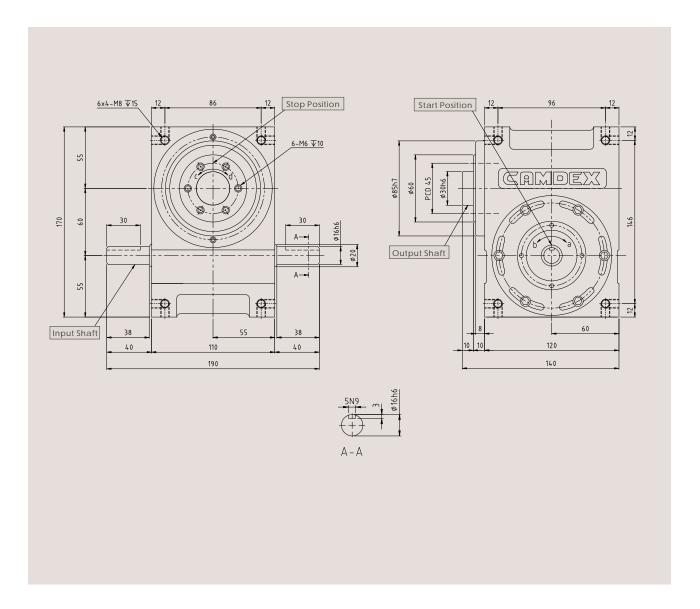
#### Product Features

This series of models are designed for heavy load capacity. They can support higher vertical, radial or axia pressure. The output shaft is disk type, with flange center, disk bolt holes and positioning pin holes. It has larger mounting area, which enhances the flatness and stability and further stabilizes the operation. It is mostly applied to the drives with larger load turn tables. This series of models are widely used in all kinds of turn table processing machines and similar application machines, auto indexing drive units and drive discs.

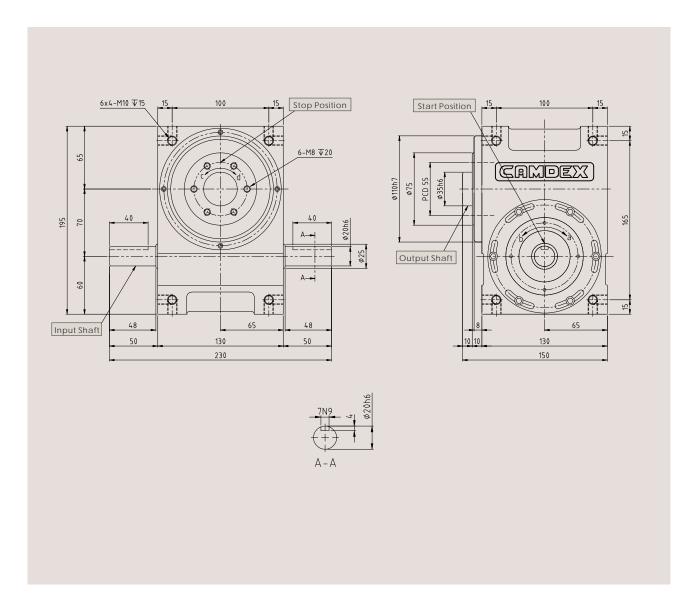
The output shaft of this series can be made into a hollow flange type, DFH, where H means the output shaft is hollow. The hollow output shaft is to allow wiring, hydraulics, compressed air lines, etc to pass through the center. The hollow shaft's inside diameter and application should be specified in the order.



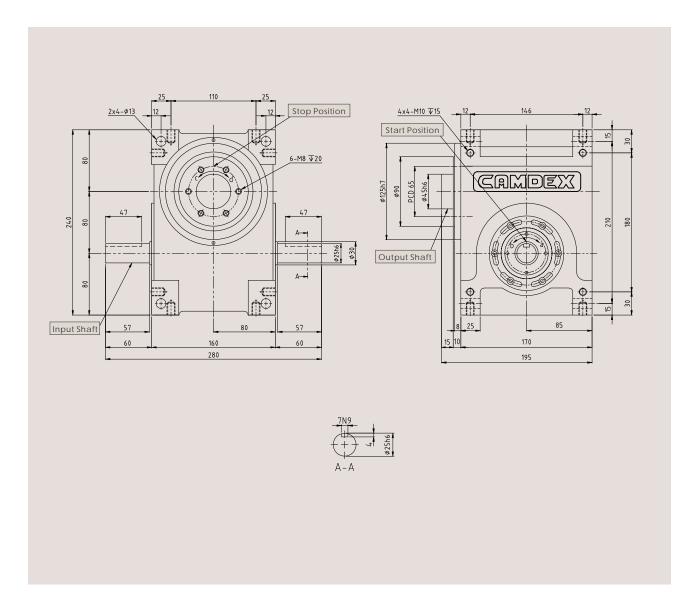
Properties	Symbol		Value
Allowable Output shaft radial load	C1	kgf	130
Allowable Output shaft axial load	C2	kgf	140
Allowable Output shaft torque	Ts	kgf-m	refer to torque chart
Allowable Input shaft radial load	C3	kgf	85
Max. Input shaft moment of deflection	C4	kgf	110
Max. Input shaft torque	C5	kgf-m	4
Input shaft GD <sup>2</sup>	C6	kgf-m²	3.2x10 <sup>-4</sup>
Positioning indexing accuracy		sec.	±60
Weight		kg	7



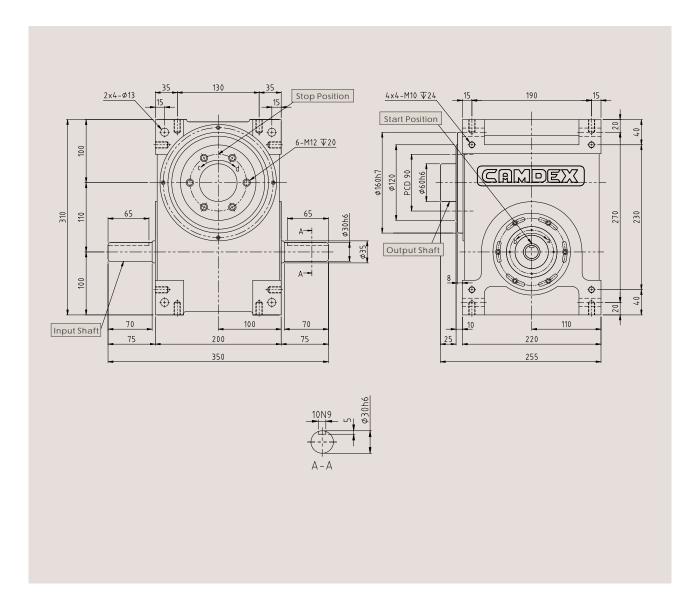
Properties	Symbol	Unit	Value
Allowable Output shaft radial load	C1	kgf	140
Allowable Output shaft axial load	C2	kgf	142
Allowable Output shaft torque	Ts	kgf-m	refer to torque chart
Allowable Input shaft radial load	C3	kgf	100
Max. Input shaft moment of deflection	C4	kgf	150
Max. Input shaft torque	C5	kgf-m	6
Input shaft GD <sup>2</sup>	C6	kgf-m²	1.9x10 <sup>-3</sup>
Positioning indexing accuracy		sec.	±45
Weight		kg	13



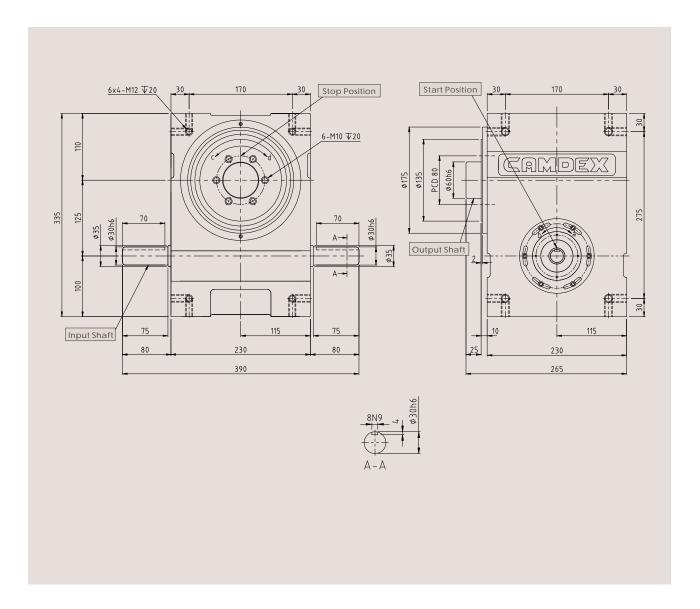
Properties	Symbol		Value
Allega e le le Control de la fita e discliere d	04	kaf	220
Allowable Output shaft radial load	C1	kgf	220
Allowable Output shaft axial load	C2	kgf	300
Allowable Output shaft torque	Ts	kgf-m	refer to torque chart
Allowable Input shaft radial load	C3	kgf	150
Max. Input shaft moment of deflection	C4	kgf	110
Max. Input shaft torque	C5	kgf-m	9.5
Input shaft GD <sup>2</sup>	C6	kgf-m²	6x10 <sup>-3</sup>
Positioning indexing accuracy		sec.	$\pm 30$
Weight		kg	18



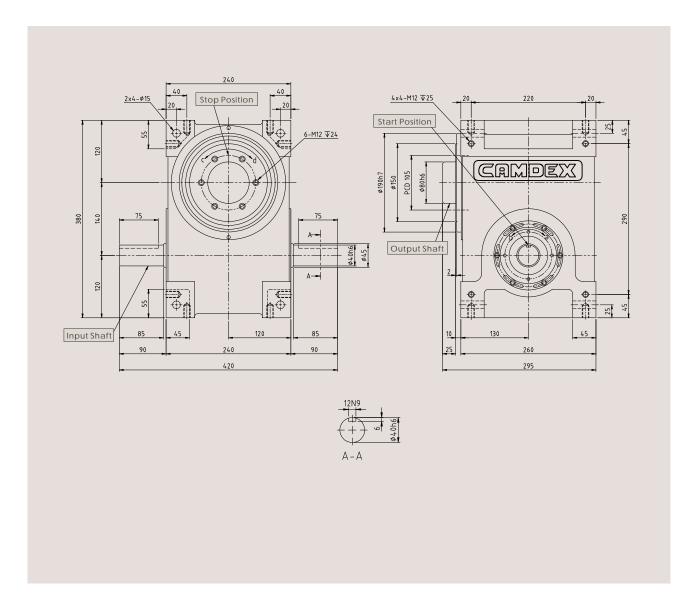
Properties	Symbol		Value
Allowable Output shaft radial load	C1	kgf	330
Allowable Output shaft axial load	C2	kgf	420
Allowable Output shaft torque	Ts	kgf-m	refer to torque chart
Allowable Input shaft radial load	C3	kgf	350
Max. Input shaft moment of deflection	C4	kgf	260
Max. Input shaft torque	C5	kgf-m	25
Input shaft GD <sup>2</sup>	C6	kgf-m²	9x10 <sup>-3</sup>
Positioning indexing accuracy		sec.	±30
Weight		kg	32



Properties	Symbol	Unit	Value
Allowable Output shaft radial load	C1	kgf	560
Allowable Output shaft axial load	C2	kgf	700
Allowable Output shaft torque	Ts	kgf-m	refer to torque chart
Allowable Input shaft radial load	C3	kgf	480
Max. Input shaft moment of deflection	C4	kgf	415
Max. Input shaft torque	C5	kgf-m	40
Input shaft GD <sup>2</sup>	C6	kgf-m²	2.8x18 <sup>-2</sup>
Positioning indexing accuracy		sec.	±30
Weight		kg	65

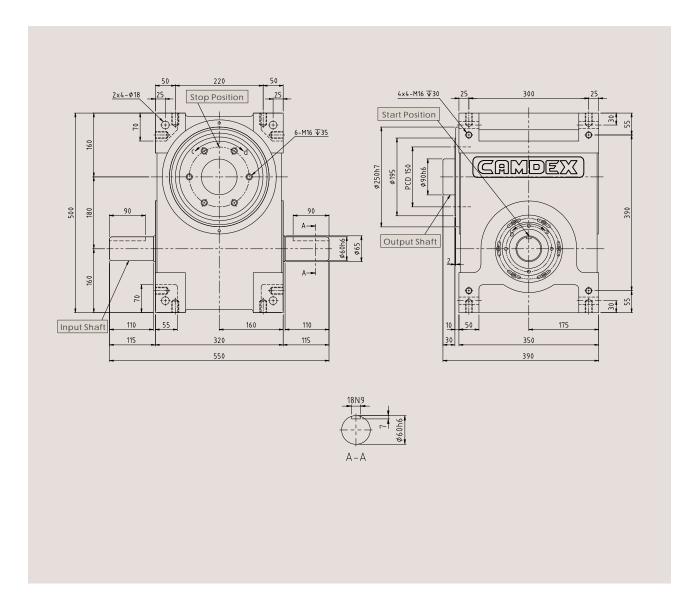


Properties	Symbol	Unit	Value
Allowable Output shaft radial load	C1	kgf	630
Allowable Output shaft axial load	C2	kgf	850
Allowable Output shaft torque	Ts	kgf-m	refer to torque chart
Allowable Input shaft radial load	C3	kgf	520
Max. Input shaft moment of deflection	C4	kgf	560
Max. Input shaft torque	C5	kgf-m	65
Input shaft GD <sup>2</sup>	C6	kgf-m²	0.28
Positioning indexing accuracy		sec.	±30
Weight		kg	78



Properties	Symbol		Value
Allega e le le Control de la fita e discliere d	04	kaf	700
Allowable Output shaft radial load	C1	kgf	760
Allowable Output shaft axial load	C2	kgf	1000
Allowable Output shaft torque	Ts	kgf-m	refer to torque chart
Allowable Input shaft radial load	C3	kgf	550
Max. Input shaft moment of deflection	C4	kgf	710
Max. Input shaft torque	C5	kgf-m	100
Input shaft GD <sup>2</sup>	C6	kgf-m²	0.11
Positioning indexing accuracy		sec.	±30
Weight		kg	90

# 180DF DF Series



Properties	Symbol	Unit	Value
Allowable Output shaft radial load	C1	kgf	1200
Allowable Output shaft axial load	C2	kgf	1500
Allowable Output shaft torque	Ts	kgf-m	refer to torque chart
Allowable Input shaft radial load	C3	kgf	1100
Max. Input shaft moment of deflection	C4	kgf	1960
Max. Input shaft torque	C5	kgf-m	340
Input shaft GD <sup>2</sup>	C6	kgf-m²	0.39
Positioning indexing accuracy		sec.	±30
Weight		kg	220

### **CAMDEX** drives

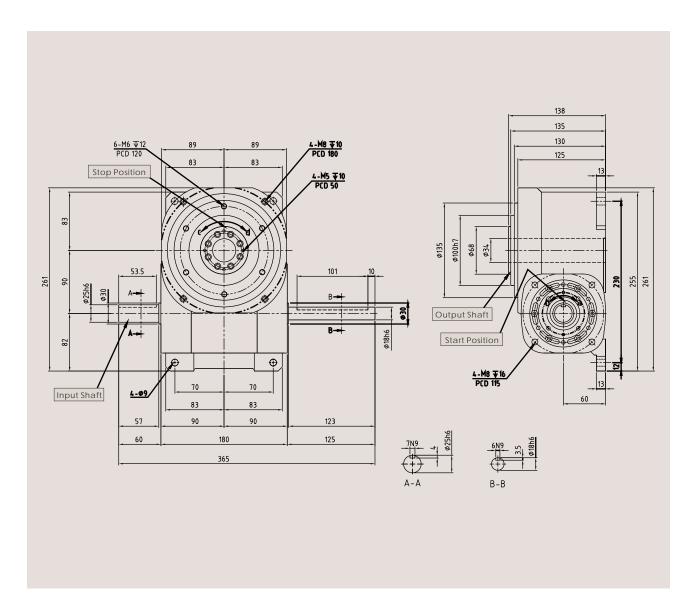


### **DA** Series 90DA / 110DA / 150DA

#### **Product Features**

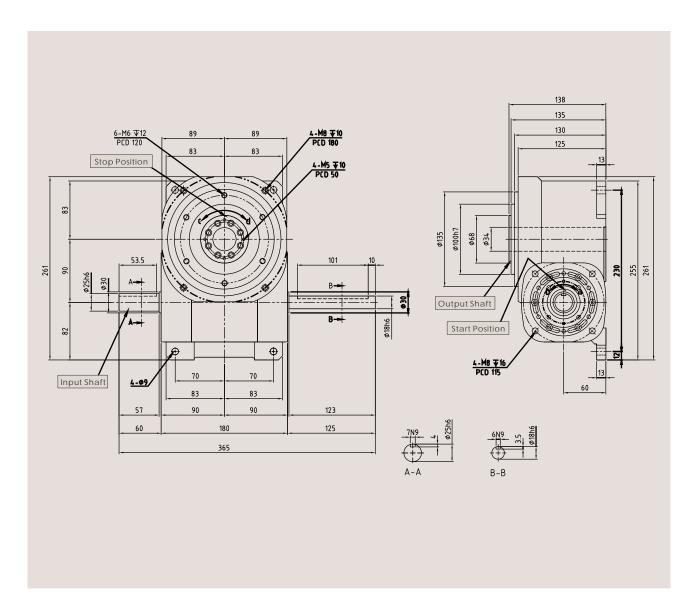
This series of models have similar size and functional features to DT series. The indexing shaft has a very high axial and radial load capacity. There is a fixed mounting flange at the center of the output shaft for installation of both static and moving automation accessories. The hollow output shaft is to allow wiring, hydraulics, compressed air lines, etc to pass through the center. As a synchronous auto index drive, it is designed to work with other dynamic or static auto machines, for heavy load applications.

## 90DA DA Series



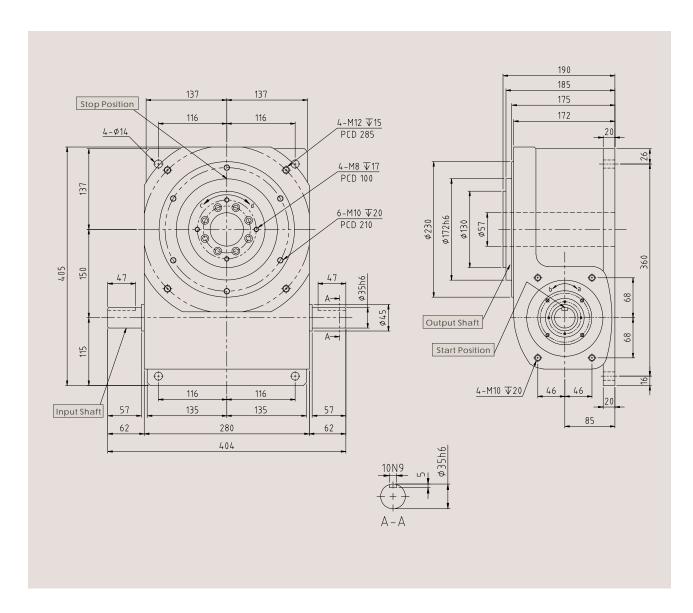
Properties	Symbol	Unit	Value
Allowable Output shaft radial load	C1	kgf	500
Allowable Output shaft axial load	C2	kgf	215
Allowable Output shaft torque	Ts	kgf-m	refer to torque chart
Allowable Input shaft radial load	C3	kgf	260
Max. Input shaft moment of deflection	C4	kgf	260
Max. Input shaft torque	C5	kgf-m	25
Input shaft GD <sup>2</sup>	C6	kgf-m²	2.5x10 <sup>-5</sup>
Positioning indexing accuracy		sec.	±30
Weight		kg	28

# 110DA DA Series

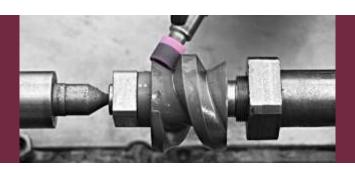


Properties	Symbol		Value
Alleria ble Orderia beeft ee dielle ee	04	kaf	700
Allowable Output shaft radial load	C1	kgf	700
Allowable Output shaft axial load	C2	kgf	350
Allowable Output shaft torque	Ts	kgf-m	refer to torque chart
Allowable Input shaft radial load	C3	kgf	310
Max. Input shaft moment of deflection	C4	kgf	360
Max. Input shaft torque	C5	kgf-m	30
Input shaft GD <sup>2</sup>	C6	kgf-m <sup>2</sup>	6x10⁻⁵
Positioning indexing accuracy		sec.	±30
Weight		kg	42

# 150DA DA Series



Properties	Symbol	Unit	Value
Allowable Output shaft radial load	C1	kgf	1200
Allowable Output shaft axial load	C2	kgf	700
Allowable Output shaft torque	Ts	kgf-m	refer to torque chart
Allowable Input shaft radial load	C3	kgf	410
Max. Input shaft moment of deflection	C4	kgf	410
Max. Input shaft torque	C5	kgf-m	40
Input shaft GD <sup>2</sup>	C6	kgf-m²	2.0x10 <sup>-3</sup>
Positioning indexing accuracy		sec.	±30
Weight		kg	86



### Working Examples and Calculations -1

#### Features of Curves

Velocity(Vm), Acceleration (Am) and Input torque (Qm) of a cam curve have a big influence in the accuracy and lifespan of the indexing drives. It is very important to select the proper cam curve.

Generally speaking, common curves include Modified Sine Curve (MS), Modified Trapezoid Curve (MT), and Modified Constant Velocity Curve (MV). Principles of selection are shown on the right:

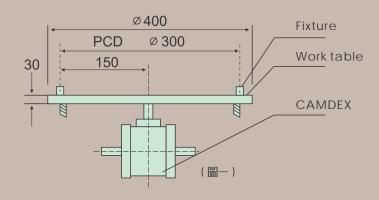
- 1 Constant speed (including start and stop)
- Constant acceleration (including start and stop)
- 3 The maximums of Am, Vm and Qm should be as small as possible
- 4 Select MS, MT with small Am and big Vm for high speed and light load application
- 6 Select MS, MCV with big Am and small Vm for low speed and heavy load application
- 6 Select MS, when speed and load is not sure

Cam curve

#### Working Example and Calculation

Example 1: for indexing drives for indexing work table Calculation:

To select indexing drives and matching motors of proper size and specification, the following calculations are performed.



Number of stops 8

Dwelling period 0.5s

Indexing period 0.25s

Table size Ø400 x 30mm

Fixture weight 4kg/section

Work piece weight 0.5kg/section

Effective rotating radius 150mm

MS

#### Calculation:

1~1 Number of stops: S=8

1~2 Rotating angle  $\theta = 360^{\circ} \times \frac{0.25}{0.25 + 0.5} = 360^{\circ} \times \frac{1}{3} = 120^{\circ}$ 

1~3 RPM of input shaft  $N = \frac{60}{t_2} \times \frac{\theta}{360} = \frac{60}{0.25} \times \frac{120}{360} = 80 \text{rpm}$ 

1~4 Cam Curve: Modified Sine Curve, therefore Vm=1.76, Am=5.53 Qm=0.987

1~5 Safety Factor for load: fe=1.8

1~6 Friction coefficient  $\mu = 0.2$ 



### Working Examples and Calculations -1

#### (1) Ti: Inertia Torque

(a) Table Weight  $W_1$ , Fixture Weight  $W_2$ , Workpiece  $W_3$ , Hence...

$$W_i = \pi \times 20^2 \times 3 \times 7.85 \times \frac{1}{1000} = 29.59 \text{ kg}$$

$$W_2 = 4 \times 8 = 32 \text{ kg}$$

$$W_3 = 0.5 \times 8 = 4 \text{ kg}$$

(b)  $\frac{1}{1}$  Inertia torque of rotating table:  $I_1$ ,  $\frac{1}{1}$  Inertia torque of fixture  $I_2$ ,  $\frac{1}{1}$  Inertia torque  $I_3$ , they are

$$I_1 = \frac{W_1 R_1^2}{2G} = \frac{29.59 \times 0.2^2}{2 \times 9.8} = 0.060 \text{ kgf} \cdot \text{m} \cdot \text{s}^2$$

$$I_2 = \frac{W_2 R_2^2}{G} = \frac{32 \times 0.15^2}{9.8} = 0.0735 \text{ kgf} \cdot \text{m} \cdot \text{s}^2$$

$$I_3 = \frac{W_3 R_3^2}{G} = \frac{4 \times 0.15^2}{9.8} = 0.0092 \text{ kgf} \cdot \text{m} \cdot \text{s}^2$$

(c) Inertia torque total: I

 $I = I_1 + I_2 + I_3 = 0.060 + 0.0735 + 0.0092 = 0.1427 \text{ kgf} \cdot \text{m} \cdot \text{s}^2$ 

as it is single flighted m = I

Ti = 226.2Am x 
$$\frac{I \cdot N^2}{S(\Theta/m)^2}$$

= 226.2 x 5.53 x 
$$\frac{0.1427 \times 80^2}{8 \times 120^2}$$

= 9.916 kgf • m

#### (2) Tf: Torque of Friction

Tf=  $\mu$  · W · R=0.2 x (29.59+32+4) x 0.15=1.968 kgf · m

### (3) Tw: Working Torque Tw=0

#### (4) Tt: Total Torque needed

Tt=Ti+Tf+Tw=9.916+1.968+0=11.884 kgf • m

Actual loaded torque

Te=Tt · fe = 11.884 x 1.8 = 21.391 kgf · m

input shaft torque Tc, Note: the starting loaded torque is considered 0, hence Tca=0

Tc =  $\frac{360}{\Theta \cdot S}$  x Qm xTe =  $\frac{360}{120 \times 8}$  x 0.987 x 21.391 = 7.917 kgf·m Figure out the power needed, assuming that the motor efficiency is 60%.

$$P = \frac{Tc \times N \times 9.8}{9550 \times 0.6}$$

$$= \frac{7.917 \times 80 \times 9.8}{9550 \times 0.6} = 1.083 \text{ kw}$$

In fact, the calculated result is the maximum starting power, and

the normal working power is: Pa = P x  $\frac{1}{2}$  = 1.083 x  $\frac{1}{2}$  = 0.542 kw

#### (5) Selecting a proper indexing drive

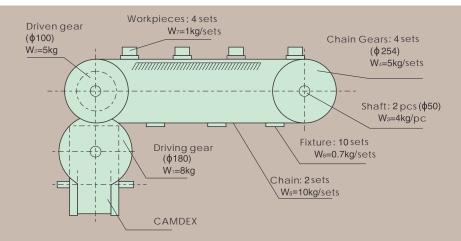
According to the calculated results and the rotating speed of the input shaft 80RPM, we find from the user manual that indexing drives with output shaft torque greater than Te can be used. As Te=Te=21.391kgf.m, Ru-110DF should be selected.



### Working Examples and Calculations -2

#### Working Example and Calculation

Example 2: indexing drives for conveyor application Indexing drives, with proper gear box for output shaft, can be used in conveyors The relevant calculation of driving the conveyor is as follows:



Designing data and information:

Convey distance:239mm

Rotating angle:  $\theta = 120^{\circ}$ 

Operation time per conveyance: 2 seconds/cycle

Speed ratio 
$$r = \frac{180}{100} = (\frac{n}{m})$$

Cam curve: Modified Sine Curve (MS)

Friction coefficient  $\mu$  =0.2

Dc = Diameter of conveyor gear pitches

Pc = Horizontal Pitch of Conveyor

r = Speed ratio

#### Calculation

2~1 Number of stops : N

$$S = \frac{\pi \times Dc \times r}{Pc} = \frac{\pi \times 25.4 \times 1.8}{23.9} = 6$$

2~2 RPM of input shaft at 2 second/cycle

$$N = \frac{60}{2} = 30 \text{rpm}$$

2~3 Cam curve: Modified Sine Curve, hence

Vm=1.76,Am=5.53,Qm=0.987

2~4 Loaded Torque: Tf

1: Static Torque (Inertia Torque) : Ti

(a) Weight of the driving gear :  $W_1=8kg$ , diameter = $\phi180$ 

Inertia torque of the driving gear: IA

$$IA = \frac{W_1R^2}{2G} = \frac{8 \times 9^2}{2 \times 980} = 0.331 (kg \cdot cm \cdot s^2)$$

(b) Inertia torque of the conveyor:

① Inertia torque of the driven gear: l2

$$I_2 = \frac{W_2(R^2 + r^2)}{2G} = \frac{5(5^2 + 2.5^2)}{2 \times 980} = 0.08(kg \cdot cm \cdot s^2)$$

2 Inertia torque of the transmission shaft: I<sub>3</sub>

$$I_{3} = \frac{W_{3} \cdot r^{2}}{2G} = \frac{4 \times 2.5^{2}}{2 \times 980} \times 2 = 0.026 (\text{kg} \cdot \text{cm} \cdot \text{s}^{2})$$

 $\ensuremath{\mathfrak{J}}$  Inertia torque of the chained gears : I4

$$I_{4} = \frac{W_{4}(Re^{2}+r^{2})}{2G} = \frac{5 \times (12.7^{2}+2.5^{2})}{2 \times 980} \times 4 = 1.71(kg \cdot cm \cdot s^{2})$$

4 Inertia torque of the chains:  $I_5$ 

$$I_5 = \frac{W_5 R_e^2}{G} = \frac{10 \times 12.7^2}{980} \times 2 = 3.29 (\text{kg} \cdot \text{cm} \cdot \text{s}^2)$$

5 Inertia torque of the fixtures: 16

$$I_{6} = \frac{W_{6}R_{e}^{2}}{G} = \frac{0.7 \times 12.7^{2}}{980} \times 10 = 1.15 (\text{kg} \cdot \text{cm} \cdot \text{s}^{2})$$



### Working Examples and Calculations -2

(6) Inertia torque of the workpieces: 17

$$I_{7} = \frac{W_{7}R_{e}^{2}}{G} = \frac{1 \times 12.7^{2}}{980} \times 4 = 0.658(kg \cdot cm \cdot s^{2})$$

Total inertia torque of the conveyor: I

$$\begin{split} IB = I_2 + I_3 + I_4 + I_5 + I_6 + I_7 \\ = 0.08 + 0.026 + 1.71 + 3.29 + 1.15 + 0.658 = 6.914 (kg \cdot cm \cdot s^2) \end{split}$$

(c) Effective inertia torque of the conveyor: IBe

$$IBe=IB(\frac{n}{m})^2=6.914\times(\frac{180}{100})^2=22.4(kg \cdot cm \cdot s^2)$$

(d) Total torque (a)+(c)之和 I=IA+IBe=0.331+22.4=22.731(kg·cm·s²)

(e) Angle Acceleration maximum of the input shaft:  $\alpha$ 

$$\alpha = Am\frac{2\pi}{S}(\frac{360}{\theta}\times\frac{N}{60})^2 = 5.53\times\frac{2\pi}{6}(\frac{360}{120}\times\frac{30}{60})^2 = 13.03(rad \cdot s^2)$$

(f) Static torque (Inertia torque)

Ti=I • 
$$\alpha$$
 =22.731×13.03=296.18(kg • cm)

2~5 Friction torque :Tf

(a) Friction torque on the conveyor: the friction load should equal the friction caused by half of the weight of the chains and fixtures on the working surface and total weight of the workpieces.

Tf = 
$$\mu \cdot W \cdot R = 0.2 \times (4 + \frac{0.7 \times 10}{2} + \frac{10 \times 2}{2}) \times 12.7$$
  
= 44.45(kg · cm)

(b) Effective friction torque of the conveyor : Tfe

Tfe=Tf(
$$\frac{n}{m}$$
)=44.45 ×  $\frac{180}{100}$ =80(kg · cm)

 $2\sim6$  Inertia torque of the workpieces : Tw Tw=0

2~7 Loaded torque : Tt 
$$\label{eq:TtTt} Tt = Tt + Tfe + Tw = 296.18 + 80 + 0 = 376.18 (kg \cdot cm) = 3.76 (kg \cdot m)$$

2~8 Actual loaded torque: Te, Loaded safety factor fe=2 Te=Tf  $\cdot$  fc=3.76 $\times$ 2=7.52

2~9 Input shaft torque: Tc

$$Tc = \frac{360}{S} \cdot \frac{1}{\theta} \cdot Qm \cdot Te + Tca = 0$$

Note: The Starting loaded torgue of the

input shaft is 0, hence Tca=0

$$Tc = \frac{360}{6} \times \frac{1}{120} \times 0.987 \times 7.52 + 0 = 3.71$$

2~10 Figure out the power needed : P assuming that the motor efficiency is  $\eta = 60\%$ 

$$P = \frac{TcxN}{975 \times \eta} (kw)$$

$$\frac{3.71 \times 30}{975 \times 0.6} = 0.19 (kw)$$

the calculated result is the maximum starting power, and the normal working power is 1/2 of the starting power.

$$0.19 \times \frac{1}{2} = 0.095 \text{kw}$$

2~11 Selecting a proper indexing drive

According to the calculated results, the rotating speed of the input shaft 30RPM, the torques reference chart in this catalogue and other relevant information, RU70DS should be selected.



No. of	Indexing	Model	Static Torque			Dynamic	Torque (k	gf-m)			Friction Torque	Bearing Dia.
Stops	Angle	Model	Ts		Ind	exing Roto	ıting Spee	d N (rpm)	)		Tx	
S	θ		(kgf-m)	50	100	150	200	300	500	700	kgf•m	(mm)
		45D	1.22	0.48	0.39	0.35	0.32	0.28	0.24		0.12	12
		60D	4.34	1.14	1.15	1.02	0.93	0.83	0.71	0.64	0.22	16
		70D	11.3	4.3	3.5	3.1	2.9	2.5	2.2	2	0.5	19
		80D	20.2	7.8	6.4	5.6	5.2	4.6	3.9	3.6	0.8	22
2	270	83D	22.4	8.4	7.1	6.3	5.9	5.2	4.1	3.9	0.9	22
	270	100D	30.5	14.8	13.7	12.8	11.6	10.2	8.3		1.3	22
		110D	49.8	19	15.4	13.7	12.5	11.1	9.5		1.6	30
		140D	80.4	28.6	23.2	20.6	18.9	16.7			2.3	40
		180D	175.4	62.9	51.1	45.2	41.5	36.7			4.1	45
		250D	377.2	136.1	110.5	97.9	89.8				7.2	60
		45D	1.22	0.58	0.47	0.42	0.38	0.34	0.29		0.12	12
		60D	4.43	1.7	1.38	1.22	1.12	0.99	0.85	0.77	0.22	16
		70D	11.3	5.2	4.2	3.7	3.4	3	2.6	2.4	0.5	19
		80D	20.2	9.4	7.7	6.8	6.2	5.5	4.7		0.8	22
	180	83D	23.2	11.4	10.2	9.6	7.3	6.1	5.1		0.9	22
	180	100D	31.7	17.3	16.5	14.3	13.8	11.5			1.3	22
		110D	49.8	22.8	18.5	16.4	15	13.3			1.6	30
		140D	80.4	34.3	27.9	24.7	22.6	20			2.3	40
		180D	175.4	75.4	61.3	54.3	49.8	44.1			4.1	45
١,		250D	377.2	163.3	132.7	117.5	107.8				7.2	60
3		45D	3.1	1.23	1	0.88	0.81	0.72	0.61	0.56	0.12	12
		60D	12.26	4.3	3.49	3.09	2.84	2.51	2.16	1.95	0.28	16
		70D	15.5	5.9	4.8	4.3	3.9	3.5	3	2.7	0.4	19
		80D	25.3	9.3	7.6	6.7	6.2	5.5	4.7	4.2	0.7	22
	270	83D	29.4	11.3	10.1	9.5	7.1	6	5.1		0.8	22
	270	100D	38.6	16.9	16.1	14.1	13.2	12.9	10.2		1.2	22
		110D	61.8	22.5	18.3	16.2	14.8	13.1	11.3		1.3	30
		140D	97.6	33.5	27.2	24.1	22.1	19.6	16.8		1.9	40
		180D	251.9	93.7	76.1	67.4	61.8	54.7			4	45
		250D	588	230.5	187.3	165.8	152.1	134.7			7	60
		45D	1.17	0.53	0.43	0.38	0.35	0.31	0.27		0.09	10
		60D	2.06	0.81	0.66	0.59	0.54	0.48	0.41		0.13	14
		70D	12.6	5.7	4.6	4.1	3.8	3.3	2.9	2.6	0.4	16
		80D	21.7	10.1	8.2	7.3	6.7	5.9	5.1	4.6	0.7	19
4	180	83D	24.2	12.3	10.1	9.2	8.1	7.2	6.4	5.8	0.8	19
4	180	100D	30.6	19.2	16.8	15.1	14.1	11.8	9.2		1.2	22
		110D	48.2	22.4	18.2	16.1	14.8	13.1	11.2		1.2	26
		140D	74.5	32.4	26.4	23.3	21.4	19			1.7	35
		180D	149.2	66	53.6	47.5	43.5	38.6			3	40
		250D	327	152.3	123.7	109.6	100.5				5.3	50



No. of	Indexing	Model	Static Torque			Dynamic	Torque (k	gf-m)			Friction Torque	Bearing Dia.
Stops	Angle	Model	Ts		Ind	exing Roto	ıting Spee	d N (rpm)	)		Tx	
S	θ		(kgf-m)	50	100	150	200	300	500	700	kgf•m	(mm)
		45D	1.75	0.71	0.57	0.51	0.47	0.41	0.35	0.32	0.1	12
		60D	5.42	1.9	1.54	1.36	1.25	1.11	0.95	0.86	0.18	14
		70D	14.8	5.5	4.5	3.9	3.6	3.2	2.7	2.5	0.3	16
		80D	25.7	9.7	7.9	7	6.4	5.7	4.9	4.4	0.6	19
4	270	83D	29.7	11.8	9.8	9.2	8.4	7.1	5.7	5.1	0.7	19
4	270	100D	39.1	18.7	16.8	14.2	12.9	11.3	9.5	8.2	0.9	22
		110D	56.9	21.5	17.5	15.5	14.2	12.6	10.8	9.8	1	26
		140D	86.5	31	25.1	22.3	20.4	18.1	15.5		1.4	35
		180D	239.2	93.4	75.9	67.2	61.6	54.6	46.8		3.2	40
		250D	528.5	210.1	170.7	151.1	138.6	122.8			5.5	50
		45D	1.22	0.79	0.64	0.57	0.52	0.46			0.12	12
		60D	4.34	2.32	1.88	1.67	1.53	1.35	1.16		0.22	16
		70D	12.5	8.2	6.7	5.9	5.4	4.8	4.1		0.5	19
		80D	20.2	12.9	10.5	9.3	8.5	7.5	6.4		0.8	22
	90	83D	22.3	14.7	12.3	11.4	10.2	9.6	7.5		0.9	22
	90	100D	33.2	26.5	23.7	21.8	19.6	16.5			1.3	22
		110D	49.8	31.1	25.3	22.4	20.6	18.2			1.6	30
		140D	80.4	46.9	38.1	33.7	30.9	27.4			2.3	40
		180D	175.4	103.1	83.7	74.1	68				4.1	45
		250D	377.2	233.1	181.2	160.5					7.2	60
		45D	2.92	1.68	1.37	1.21	1.11	0.98	0.84	0.76	0.12	12
		60D	11.69	5.77	4.83	4.27	3.92	3.47	2.98	2.69	0.3	16
		70D	14.6	8.2	6.6	5.9	5.4	4.8	4.1	3.7	0.5	22
		80D	35.1	20	16.3	14.4	13.2	11.7	10	9.1	0.9	26
6	120	83D	37.2	23.2	17.2	15.1	14.3	12.6	10.7	9.8	1.1	26
Ĭ	120	100D	48.4	28.4	24.6	22.3	20.8	18.5	14.7		1.2	26
		110D	60.7	32.9	26.7	23.7	21.7	19.2	16.5		1.4	30
		140D	115.7	60.3	49	43.4	39.8	35.2			2.3	40
		180D	238.5	129	104.8	92.8	85.1	75.3			4.2	45
		250D	550	315.5	256.3	226.9	208.2				7.4	80
		45D	3.5	1.63	1.32	1.17	1.08	0.95	0.82	0.74	0.11	12
		60D	13.43	5.64	4.58	4.06	3.72	3.3	2.83	2.56	0.26	16
		70D	17.2	7.8	6.4	5.6	5.2	4.6	3.9	3.6	0.4	22
		80D	41.4	19.3	15.7	13.9	12.7	11.3	9.7	8.7	0.8	26
	180	83D	43.6	21.8	18.6	15.4	13.7	12.8	10.3	9.2	0.9	26
		100D	57.2	34.5	30.6	27.1	24.6	21.6	18.1	15.9	1.3	26
		110D	85.9	39.3	31.9	28.3	25.9	23	19.7	17.8	1.4	30
		140D	133	57.3	46.5	41.2	37.8	33.4	28.7		2	40
		180D	375.5	176.6	143.5	127	116.5	103.2	88.5		4.3	60
		250D	873.9	425.4	345.5	305.9	280.7	248.5			8	80



No.	Indexing		Static Torque			Dynamic	Torque (k	(gf-m)			Friction	Bearing	
of Stops	Angle	Model	Ts		Ind	exing Rota	iting Spee	d N (rpm)			Torque Tx	Dia.	
S	θ		(kgf-m)	50	100	150	200	300	500	700	kgf•m	(mm)	
		45D	3.8	1.56	1.27	1.12	1.03	0.91	0.78	0.71	0.1	12	
		60D	14.25	5.33	4.33	3.83	3.52	3.11	2.67	2.42	0.24	16	
		70D	18.5	7.5	6.1	5.4	4.9	4.4	3.7	3.4	0.4	22	
		80D	44.6	18.4	14.9	13.2	12.1	10.7	9.2	8.3	0.7	26	
	240	83D	46.7	20.1	18.5	16.1	14.7	13.2	10.5	9.6	0.8	26	
	240	100D	62.9	33.1	28.5	24.3	22.7	20.9	16.4	13.6	1.2	26	
		110D	92.2	37.4	30.3	26.9	24.6	21.8	18.7	16.9	1.3	30	
		140D	141.1	54.1	43.9	38.9	35.7	31.6	27.1	24.5	1.8	40	
		180D	404.8	168.3	136.7	121	111	98.3	84.3	76.2	4	60	
		250D	965.3	410.1	333.1	295	270.6	239.6			7.3	80	
		45D	3.9	1.52	1.24	1.1	1.01	0.89	0.76	0.69	0.1	12	
		60D	14.5	5.19	4.22	3.73	3.42	3.03	2.6	2.35	0.23	16	
		70D	18.8	7.3	5.9	5.2	4.8	4.2	3.6	3.3	0.4	22	
		80D	45.6	17.9	14.6	12.9	11.8	10.5	9	8.1	0.7	26	
	270	83D	47.3	18.4	16.9	14.1	13.2	11.6	9.6	8.7	0.8	26	
6	270	100D	63.3	32.5	27.2	24.6	22.9	20.2	16.9	14.2	1.2	26	
	5 270	110D	94.1	36.4	29.6	26.2	24	21.3	18.3	16.5	1.3	30	
		140D	143.6	52.7	42.8	37.9	34.8	30.8	26.4	23.9	1.8	40	
			180D	414	164.2	133.4	118.1	108.4	96	82.3	74.4	3.8	60
		250D	995.3	402	326.5	289.1	265.2	234.8	201.5		7.1	80	
		45D	3.97	1.49	1.21	1.07	0.98	0.87	0.75	0.68	0.1	12	
		60D	14.68	5.06	4.11	3.64	3.34	2.96	2.54	2.29	0.23	16	
		70D	19.1	7.1	5.8	5.1	4.7	4.1	3.6	3.2	0.3	22	
		80D	46.4	17.5	14.2	12.6	11.6	10.2	8.8	7.9	0.7	26	
	200	83D	48.3	18.2	15.1	13.6	12.4	11.8	9.2	8.4	0.8	26	
	300	100D	62.5	30.5	24.3	22.1	20.6	18.7	15.4	14.2	1.1	26	
		110D	95.6	35.6	28.9	25.6	23.5	20.8	17.8	16.1	1.3	30	
		140D	145.4	51.4	41.7	36.9	33.9	30	25.7	23.3	1.7	40	
		180D	421	160.5	130.3	115.4	105.9	93.7	80.4	72.7	3.8	60	
		250D	1018.5	394	320	283.4	259.9	230.2	197.5		6.9	80	
		45D	1.5	0.96	0.78	0.69	0.63	0.56	0.48		0.09	12	
		60D	2.06	1.11	0.9	0.8	0.73	0.65	0.56		0.13	14	
		70D	12.6	6.9	6.3	5.6	5.2	4.6	3.9	3.5	0.4	16	
		80D	21.5	11.4	11.4	10.2	9.4	8.3	7.1		0.7	19	
		83D	23.2	13.5	13.1	12.6	11.5	10.4	8.4		0.8	26	
8	90	100D	34.5	28.1	23.2	21.1	19.2	16.3			1.1	26	
		110D	48.2	30.6	24.8	22	20.2	17.9			1.2	26	
		140D	74.5	44.3	36	31.9	29.2	25.9			1.7	35	
		180D	149.2	90.2	73.2	64.8	59.5				3	40	
		250D	327	208.1	169	149.7					5.3	50	



No. of	Indexing	Model	Static Torque			Dynamic	Torque (k	(gf-m)			Friction Torque	Bearing Dia.
Stops	Angle	Model	Ts (leaf ma)		Inde	exing Rota	iting Spee	d N (rpm)	)		Tx	
S	θ		(kgf-m)	50	100	150	200	300	500	700	kgf•m	(mm)
		45D	2.15	1.25	1.02	0.9	0.83	0.73	0.63	0.57	0.1	12
		60D	5.29	2.65	2.15	1.91	1.75	1.55	1.33	1.2	0.18	14
		70D	14.2	7.4	6.2	5.5	5	4.4	3.8	3.5	0.4	16
		80D	24.7	11.9	11	9.7	8.9	7.9	6.8	6.1	0.6	19
	120	83D	26.5	13.2	12.3	11	10.1	9.1	8	7.3	0.7	26
	120	100D	36.3	21.2	16.6	13.8	12	10.1	8.4		1	26
		110D	54.7	29.9	24.3	21.5	19.7	17.5	15		1.1	26
		140D	86.6	45.6	37.1	32.8	30.1	26.7	22.9		1.6	35
		180D	167.3	87.6	71.2	63	57.8	51.2			2.8	50
		250D	503.2	290.2	235.7	208.7	191.4				5.7	60
		45D	2.33	1.22	0.99	0.88	0.81	0.71	0.61	0.55	0.09	12
		60D	5.52	2.53	2.06	1.82	1.67	1.48	1.27	1.15	0.17	14
		70D	15.2	7.4	6	5.3	4.9	4.3	3.7	3.3	0.3	16
		80D	26.5	12.3	10.6	9.4	8.6	7.7	6.6	5.9	0.6	19
	150	83D	28.4	14.6	12.9	11.7	10.9	10	8.4	7.4	0.7	26
	130	100D	38.5	20.5	16.1	13.4	11.3	10.6	9.5		0.9	26
		110D	58.7	29	23.5	20.8	19.1	16.9	14.5		1	26
		140D	92.2	44.1	35.8	31.7	29.1	25.7	22.1		1.4	35
		180D	246.6	125.5	102	90.3	82.8	73.3	62.9		3.1	50
8		250D	549.1	283.5	230.3	203.9	187	165.6			5.3	60
		45D	2.44	1.18	0.96	0.85	0.78	0.69	0.59	0.54	0.09	12
		60D	5.66	2.43	1.97	1.75	1.6	1.42	1.22	1.1	0.17	14
		70D	16.8	8	6.5	5.8	5.3	4.7	4	3.6	0.3	16
		80D	30.4	14.7	11.9	10.5	9.7	8.6	7.3	6.6	0.6	19
	180	83D	32.3	17.1	13.4	12.1	11.3	10.4	8.8	7.8	0.7	26
	100	100D	40.6	24.3	16.6	13.8	12.3	11.2	9.4	8.5	1	26
		110D	74.3	35.7	29	25.7	23.6	20.9	17.9	16.2	1.1	26
		140D	113.4	51.4	41.8	37	33.9	30	25.8	23.3	1.6	35
		180D	257.3	121.4	98.6	87.3	80.1	70.9	60.9		2.9	50
		250D	739.7	373	303	268.3	246.1	217.9			5.8	60
		45D	2.52	1.15	0.93	0.83	0.76	0.67	0.58	0.52	0.09	12
		60D	5.75	2.33	1.9	1.68	1.54	1.36	1.17	1.06	0.16	14
		70D	17.3	7.7	6.3	5.6	5.1	4.5	3.9	3.5	0.3	16
		80D	31.3	14.2	11.5	10.2	9.4	8.3	7.1	6.4	0.6	19
	210	83D	34.3	16.8	13.1	11.8	10.2	9.6	7.8	6.6	0.7	26
		100D	42.5	23.4	16.4	13.2	11.5	10.3	8.2	7.2	1	26
		110D	76.5	34.6	28.1	24.9	22.8	20.2	17.3	15.7	1.1	26
		140D	115.9	49.6	40.3	35.7	32.7	29	24.9	22.5	1.5	35
		180D	264.5	117.5	95.5	84.5	77.5	68.7	58.9		2.8	50
		250D	767.6	326.8	294.7	261	239.4	212			5.6	60



No. of	Indexing	Madal	Static Torque				Friction	Bearing				
Stops	Angle	Model	Ts (leaf ma)		Ind	exing Rota	iting Spee	d N (rpm)	)		Torque Tx	Dia.
S	θ		(kgf-m)	50	100	150	200	300	500	700	kgf•m	(mm)
		45D	2.58	1.12	0.91	0.8	0.74	0.65	0.56	0.51	0.09	12
		60D	5.81	2.25	1.83	1.62	1.49	1.32	1.13	1.02	0.16	14
		70D	17.6	7.5	6.1	5.4	5	4.4	3.8	3.4	0.3	16
		80D	31.9	13.8	11.2	9.9	9.1	8	6.9	6.2	0.6	19
	240	83D	34.7	15.4	12.8	11.4	10.1	9.4	7.4	6.5	0.7	26
	240	100D	43.1	22.8	16.2	13	11.1	10.1	8.1	6.8	1	26
		110D	77.9	33.5	27.2	24.1	22.1	19.6	16.8	15.2	1	26
		140D	117.7	48	39	34.5	31.7	28.1	24.1	21.8	1.5	35
		180D	316.4	138.7	112.7	99.8	91.5	81	69.5	62.8	3.1	50
		250D	787.6	353.1	286.8	254	233	206.3	177		5.5	60
		45D	2.62	1.09	0.88	0.78	0.72	0.63	0.54	0.49	0.08	12
		60D	5.85	2.18	1.77	1.57	1.44	1.28	1.09	0.99	0.16	14
		70D	17.8	7.3	5.9	5.2	4.8	4.3	3.7	3.3	0.3	16
		80D	32.3	13.4	10.9	9.6	8.8	7.8	6.7	6.1	0.6	19
8	270	83D	35.6	16.1	12.4	11	9.8	9.1	7.2	6.8	0.7	26
0	270	100D	45.2	21.3	15.8	12.3	10.8	9.3	7.6	7.2	1	26
		110D	79	32.6	26.5	23.4	21.5	19	16.3	14.8	1	26
		140D	118.9	46.6	37.9	33.5	30.7	27.2	23.4	21.1	1.4	35
		180D	320.6	134.8	109.5	96.9	88.9	78.7	67.6	61.1	3	50
		250D	802.2	344	279.4	247.4	226.9	200.9	172.4		5.3	60
		45D	2.65	1.06	0.86	0.76	0.7	0.62	0.53	0.48	0.08	12
		60D	5.88	2.12	1.72	1.53	1.4	1.24	1.06	0.96	0.15	14
		70D	18	7.1	5.8	5.1	4.7	4.1	3.6	3.2	0.3	16
		80D	32.6	13	10.6	9.4	8.6	7.6	6.5	5.9	0.6	19
	300	83D	36	15.9	12.1	10.7	9.5	8.8	6.9	6.5	0.7	26
	300	100D	45.8	20.6	15.1	11.6	11.4	9.6	7.9	8.1	1	26
		110D	79.8	31.7	25.8	22.8	20.9	18.5	15.9	14.4	1	26
		140D	119.8	45.3	36.8	32.6	29.9	26.5	22.7	20.5	1.4	35
		180D	323.7	131.2	106.6	94.4	86.6	76.7	65.8	59.5	3	50
		250D	813.2	335.5	272.5	241.3	221.4	196	168.2		5.2	60
		45D	1.15	0.65	0.52	0.4	0.33	0.29	0.21		0.08	10
		60D	1.76	0.94	0.76	0.68	0.62	0.55	0.47		0.1	12
		70D	25	3	2.5	2.2	2	1.8	1.5		0.3	14
		80D	22.7	8.4	8.4	8.4	8.4	8.3	7.1	6.4	0.6	16
10	90	83D	23.1	8.7	8.6	8.7	8.7	8.6	7.4	6.8	0.7	19
10	30	100D	28.4	16.4	14.3	12.2	10.6	10.1			0.8	22
		110D	36.2	22.3	18.1	16.1	14.7	13.1			0.9	22
		140D	46	26	21.1	18.7	17.2	15.2			1.1	22
		180D	108.7	63.2	51.4	45.5	41.7				2.2	35
	<u> </u>	250D	312.7	198.4	161.1	142.7					4.3	40



No. of	Indexing	Model	Static Torque	que (ng. m)							Friction Torque	Bearing Dia.
Stops	Angle	Model	Ts (leaf ma)		Inde	exing Rota	iting Spee	d N (rpm)	)		Tx	
S	θ		(kgf-m)	50	100	150	200	300	500	700	kgf•m	(mm)
		45D	1.15	0.7	0.62	0.49	0.41	0.33	0.25		0.07	10
		60D	2.33	1.18	0.96	0.85	0.78	0.69	0.59	0.54	0.12	12
		70D	5.5	2.9	2.4	2.1	1.9	1.7	1.5	1.3	0.3	14
		80D	23.1	8.8	8.8	8.8	8.8	8	6.9	6.2	0.6	16
	120	83D	24.8	9.3	9.2	8.9	8.9	8.4	7.4	6.8	0.7	19
	120	100D	30.2	15.7	14.6	13.1	10.9	10.7			0.8	22
		110D	39.7	21.4	17.4	15.4	14.2	12.5	10.8		0.8	22
		140D	73.8	38.7	31.4	27.8	25.5	22.6	19.4		1.2	26
		180D	144.1	76.8	62.4	55.2	50.7	44.9			2.3	35
		250D	410.8	235.1	190.9	169.1	155.1				4.5	45
		45D	1.35	0.63	0.54	0.43	0.36	0.29	0.2		0.06	10
		60D	2.44	1.07	0.87	0.77	0.71	0.63	0.54	0.48	0.11	12
		70D	5.9	2.7	2.2	1.9	1.8	1.6	1.3	1.2	0.2	14
		80D	27.2	9.2	9.2	9.1	8.3	7.4	6.3	5.7	0.5	16
	180	83D	28.9	9.8	9.7	9.5	9.2	8.8	7.2	6.8	0.6	19
	180	100D	35.2	10.6	10.3	9.9	9.7	9.4	8.6	8.4	0.6	22
		110D	42.9	19.7	16	14.2	13	11.5	9.9	8.9	0.7	22
		140D	79.5	35.6	28.9	25.6	23.5	20.8	17.8	16.1	1.1	26
		180D	191.7	90.7	73.7	65.3	59.9	53	45.5		2.4	40
10		250D	453.9	218.8	177.7	157.4	144.4	127.8			4	45
10		45D	1.45	0.59	0.48	0.37	0.3	0.27	0.18		0.06	10
		60D	2.49	0.99	0.8	0.71	0.65	0.58	0.5	0.45	0.11	12
		70D	6	2.5	2	1.8	1.6	1.5	1.2	1.1	0.2	14
		80D	28.1	9.3	9.3	8.5	7.8	6.9	5.9	5.3	0.5	16
	240	83D	30.2	10	9.7	9.5	9.1	8.7	7.1	6.5	0.5	19
	240	100D	36.2	12.5	12.1	11.8	11.3	10.6	9.6	9.1	0.6	22
		110D	44.2	18.4	14.9	13.2	12.1	10.7	9.2	8.3	0.7	22
		140D	81.8	33.1	26.9	23.8	21.8	19.3	16.6	15	1	26
		180D	197.1	84.4	68.6	50.7	55.7	49.3	42.3	38.2	2.2	40
		250D	636.1	291.2	236.6	209.5	192.1	170.1	146		4.5	45
		45D	1.5	0.56	0.45	0.34	0.3	0.26	0.17		0.06	10
		60D	2.5	0.96	0.78	0.69	0.63	0.56	0.48	0.43	0.1	12
		70D	6.1	2.4	2	1.7	1.6	1.4	1.2	1.1	0.2	14
		80D	28.3	9.4	9.3	8.2	7.5	6.7	5.7	5.2	0.5	16
	270	83D	30.8	9.8	9.5	9.3	8.8	8.4	6.9	6.3	0.5	19
		100D	36.6	12.3	11.8	11.2	10.9	9.5	9.1	8.4	0.6	22
		110D	44.6	17.8	14.5	12.8	11.8	10.4	8.9	8.1	0.7	22
		140D	82.5	32.1	26	23.1	21.2	18.7	16.1	14.5	1	26
		180D	198.6	81.8	66.4	58.8	54	47.8	41	37.1	2.2	40
		250D	643.9	282.8	229.7	203.4	186.6	165.2	141.8		4.4	45



No. of	Indexing	Madal	Static Torque			Dynamic	Torque (k	(gf-m)			Friction	Bearing
Stops	Angle	Model	Ts (leaf ma)		Ind	exing Rota	iting Spee	d N (rpm)	)		Torque Tx	Dia.
S	θ		(kgf-m)	50	100	150	200	300	500	700	kgf•m	(mm)
		45D	1.52	0.54	0.43	0.33	0.29	0.25	1.6		0.06	10
		60D	2.51	0.93	0.76	0.67	0.61	0.54	0.47	0.42	0.1	12
		70D	6.1	2.3	1.9	1.7	1.5	1.4	1.2	1.1	0.2	14
		80D	28.5	9.4	9	8	7.3	6.5	5.6	5.5	0.5	16
10	300	83D	31.3	9.7	9.4	9.2	9	8.1	6.8	6.2	0.5	19
10	300	100D	37.1	12.1	11.5	10.9	10.4	9.3	8.8	8.1	0.6	22
		110D	44.8	17.3	14.1	12.5	11.4	10.1	8.7	7.8	0.7	22
		140D	83	31.2	25.3	22.4	20.6	18.2	15.6	14.1	1	26
		180D	199.8	79.5	64.6	57.2	52.4	46.4	39.8	36	2.2	40
		250D	649.6	275.3	223.6	198	181.6	160.8	138		4.4	45
		45D	0.5	0.31	0.21	0.19	0.15	0.13			0.06	10
		60D	0.94	0.49	0.4	0.35	0.32	0.29			0.09	10
		70D	2.7	1.6	1.3	1.1	1.1	0.9			0.2	12
		80D	24.3	8.7	8.7	8.7	8.7	8.7	7.9	7.1	0.6	16
	90	83D	25.3	8.9	8.9	8.8	8.8	8.8	8.1	7.6	0.7	16
	30	100D	28.2	12.2	12.1	11.8	11.6	10.2			0.7	19
		110D	35.5	16.8	16.8	15.9	14.6	12.9			0.8	19
		140D	48.3	27.9	22.7	20.1	18.4	16.3			1	22
		180D	110.9	65.7	53.3	47.2	43.3	38.4			2	30
		250D	246.7	151.7	123.3	109.1					3.4	40
		45D	1.42	0.8	0.6	0.51	0.45	0.4			0.06	10
		60D	1.91	0.96	0.78	0.69	0.63	0.56	0.48	0.43	0.09	10
		70D	2.8	1.5	1.2	1.1	1	0.9	0.8		0.2	12
		80D	26.1	9	9	9	9	8.7	7.5	6.8	0.5	16
12	120	83D	26.7	9.3	9.3	9.2	9.1	9	8.4	8	0.6	16
12	120	100D	29.3	13.5	13.2	12.8	10.1	9.8	9		0.7	19
		110D	38.4	17.5	17.1	15.2	13.9	12.3	10.6		0.7	19
		140D	51.4	26.4	21.5	19	17.4	15.4			0.9	22
		180D	118.2	62.2	50.5	44.7	41	36.3			1.9	30
		250D	367.6	211.5	171.8	152.1	139.6				3.7	40
		45D	1.42	0.71	0.54	0.47	0.4	0.35			0.06	10
		60D	1.97	0.86	0.7	0.62	0.57	0.5	0.43	0.39	0.09	10
		70D	3	1.4	1.1	1	0.9	0.8	0.7	0.6	0.2	12
		80D	27.8	9.3	9.3	9.3	9	8	6.8	6.2	0.5	16
	180	83D	28.1	9.8	9.8	9.8	9.3	9	7.9	7.5	0.6	16
		100D	31.2	14.6	14.3	12.6	12.3	10.8	8.8	8	0.7	19
		110D	40.9	18.1	15.6	13.9	12.7	11.3	9.7	8.7	0.7	19
		140D	79.3	37.2	30.2	26.7	24.5	21.7	18.6	16.8	1	22
		180D	157.1	75.3	61.2	54.2	49.7	44	37.7		2	35
		250D	395.5	194.3	157.8	139.7	128.2	113.5			3.4	40



No. of	Indexing	Model	Static Torque			Dynamic	Torque <b>(k</b>	gf-m)			Friction Torque	Bearing Dia.
Stops	Angle O	wodei	Ts (kgf-m)		Inde	exing Rota	ting Spee	d N (rpm)	)		Tx	(mm)
5	D		(kgi-iii)	50	100	150	200	300	500	700	kgf•m	(111111)
		45D	1.5	0.61	0.5	0.43	0.36	0.3			0.06	10
		60D	2	0.8	0.65	0.57	0.53	0.47	0.4	0.36	0.09	10
		70D	3	1.3	1	0.9	0.8	0.7	0.6	0.6	0.2	12
		80D	28.5	9.4	9.4	9.1	8.4	7.4	6.4	5.7	0.5	16
	240	83D	29.6	9.6	9.6	9.5	8.7	7.7	6.7	6	0.6	16
	240	100D	33.4	14.3	14.1	11.1	10.9	9.8	8.2	7.6	0.6	19
		110D	41.9	17.9	14.5	12.9	11.8	10.5	9	8.1	0.6	19
		140D	80.7	34.4	28	24.8	22.7	20.1	17.3	15.6	1	22
		180D	160.2	69.8	56.7	50.2	46	40.8	35	31.6	1.9	35
		250D	480.4	221.4	179.8	159.2	146.1	129.3	111		3.7	40
		45D	1.55	0.58	0.49	0.4	0.35	0.29			0.06	10
		60D	2.01	0.77	0.63	0.55	0.51	0.45	0.39	0.35	0.09	10
		70D	3.1	1.2	1	0.9	0.8	0.7	0.6	0.6	0.2	12
		80D	28.6	9.4	9.4	8.8	8.1	7.2	6.1	5.6	0.5	16
12	270	83D	29.8	9.5	9.5	8.9	8.4	7.5	6.7	5.8	0.5	16
12	270	100D	34.3	14.5	14.3	14	13	10.8	9.2	8.9	0.6	19
		110D	46.4	20	16.2	14.4	13.2	11.7	10	9	0.7	19
		140D	81.2	33.3	27.1	24	22	19.5	16.7	15.1	1	22
		180D	161.1	67.5	54.8	48.8	44.6	39.4	33.8	30.6	1.9	35
		250D	484.4	214.6	174.3	154.3	141.6	125.3	107.5		3.7	40
		45D	1.55	0.52	0.47	0.38	0.33	0.27			0.06	10
		60D	2.01	0.75	0.61	0.54	0.49	0.44	0.37	0.34	0.09	10
		70D	3.1	1.2	1	0.9	0.8	0.7	0.6	0.5	0.2	12
		80D	28.8	9.4	9.4	8.6	7.9	7	6	5.4	0.5	16
	200	83D	30.2	9.5	9.5	8.9	8.7	7.8	6.8	6	0.5	16
	300	100D	35.1	14.3	14.1	13.6	12.3	10.5	8.8	8.4	0.6	19
		110D	46.6	19.4	15.8	14	12.8	11.3	9.7	8.8	0.7	19
		140D	81.5	32.3	26.3	23.3	21.3	18.9	16.2	14.7	1	22
		180D	161.8	65.6	53.2	47.1	43.3	38.3	32.9	29.7	1.9	35
		250D	487.2	208.5	169.4	150	137.6	121.8	104.5		3.6	40
		110D	36.2	12.5	12.5	12.5	12.5	12.5	11.4		0.7	16
	90	140D	46.3	20.8	20.8	19.6	17.9	15.9			0.9	19
	1DWELL	180D	65.9	37.6	30.5	27	24.8				1.4	22
		250D	178.6	108.6	88.2	78.1					2.5	30
1.0		45D	1.5	0.7	0.51	0.43	0.4	0.35			0.1	12
16		60D	2.06	1.11	0.9	0.8	0.73	0.65			0.13	14
	90	70D	12.6	6.9	6.3	5.6	5.2	4.6	3.9		0.4	16
	2DWELL	80D	21.5	11.4	11.4	10.2	9.4	8.3			0.7	19
	2DWELL	83D	22.5	11.7	11.6	10.5	9.7	8.6			0.7	19
		100D	28.4	12	11.9	10.8	10.1	8.9			0.7	22



No. of	Indexing	Model	Static Torque	lue							Friction Torque	Bearing Dia.
Stops	Angle	Model	Ts		Ind	exing Rota	iting Spee	d N (rpm)	)		Tx	
S	θ		(kgf-m)	50	100	150	200	300	500	700	kgf•m	(mm)
		110D	38.1	12.8	12.8	12.8	12.8	12.5	10.7		0.7	16
	120	140D	48.1	21.1	20.6	18.3	16.8	14.8	12.7		0.8	19
	1DWELL	180D	68.5	35.2	28.6	25.3	23.2	20.5			1.4	22
		250D	228.5	128.1	104	92.1	84.5				2.7	30
		45D	1.67	0.98	0.79	0.7	0.6	0.57	0.49		0.1	12
		60D	5.29	2.65	2.15	1.91	1.75	1.55	1.33	1.2	0.18	14
	120	70D	15.1	8.6	7	6.2	5.6	5	4.3	3.9	0.4	16
	2DWELL	80D	24.8	12.2	11.4	10.1	9.2	8.2	7		0.6	19
		83D	25.3	12.5	11.7	10.4	9.5	8.4	7.4		0.7	19
		100D	29.2	12.6	12.6	12.5	10.1	9.5	9.1		0.7	22
		110D	39.6	18.1	18.1	13.1	12.7	11.3	9.7	8.7	0.6	16
	180	140D	49.4	21.4	18.5	16.4	15	13.3	11.4	10.3	0.8	19
	1DWELL	180D	104.5	49.6	40.3	35.6	32.7	29	24.8		1.5	26
		250D	295.1	149.1	121.1	107.3	98.4	87.1			2.8	35
		45D	1.9	0.92	0.75	0.66	0.61	0.54	0.46	0.42	0.09	12
		60D	5.66	2.43	1.97	1.75	1.6	1.42	1.22	1.1	0.17	14
	180	70D	16.8	8	6.5	5.8	5.3	4.7	4	3.6	0.3	16
	2DWELL	80D	31.4	15.6	12.7	11.3	10.3	9.1	7.8	7.1	0.6	19
16		83D	32.5	16.9	13.1	11.7	10.8	9.4	8.1	7.4	0.6	19
16		100D	33.2	17.1	13.6	12.5	11.3	10	8.4	7.7	0.6	22
		110D	40.2	18.2	16.2	12.8	11.7	10.4	8.9	8.1	0.6	16
	240	140D	49.9	21	17.1	15.1	13.9	12.3	10.5	9.5	0.7	19
	1DWELL	180D	105.7	45.7	37.1	32.9	30.2	26.7	22.9	20.7	1.5	26
		250D	299.7	137.9	112	99.2	91	80.5			2.7	35
		45D	2.01	0.87	0.71	0.62	0.57	0.51	0.44	0.39	0.09	12
		60D	5.81	2.25	1.83	1.62	1.49	1.32	1.13	1.02	0.16	14
	240	70D	17.6	7.5	6.1	5.4	5	4.4	3.8	3.4	0.3	16
	2DWELL	80D	33.4	14.8	12	10.6	9.8	8.6	7.4	6.7	0.6	19
		83D	34.3	15.1	12.3	10.9	9.1	8.9	7.7	7.1	0.6	19
		100D	35.7	15.6	12.8	11.2	9.8	9.2	8.1	7.8	0.6	22
		110D	40.4	18.2	16.2	12.4	11.4	10.1	8.6	7.8	0.6	16
	270	140D	50.1	20.3	16.5	14.6	13.4	11.9	10.2	9.2	0.7	19
	1DWELL	180D	106	44.2	35.9	31.8	29.2	25.8	22.1	20	1.4	26
		250D	301	133.4	108.3	95.9	88	77.9	66.8		2.7	35
		45D	2.04	0.84	0.69	0.61	0.56	0.49	0.42	0.38	0.08	12
	270	60D	5.85	2.18	1.77	1.57	1.44	1.28	1.09	0.99	0.16	14
	2DWELL	70D	17.8	7.3	5.9	5.2	4.8	4.3	3.7	3.3	0.3	16
		80D	33.9	14.4	11.7	10.4	9.5	8.4	7.2	6.5	0.6	19



No.	Indexing	Model	Static Torque			Dynamic	Torque (k	(gf-m)			Friction Torque	Bearing Dia.
Stops	Angle	Model	Ts (kgf m)		Ind	exing Rota	iting Spee	d N (rpm	)		Tx	
S	θ		(kgf-m)	50	100	150	200	300	500	700	kgf•m	(mm)
		110D	40.5	18.2	14.2	12	11	9.8	8.4	7.6	0.6	16
	300	140D	50.2	19.7	16	14.2	13	11.5	9.9	8.9	0.7	19
	1DWELL	180D	106.3	42.9	34.8	30.8	28.3	25	21.5	19.4	1.4	26
		250D	302	129.4	105.1	93.1	85.4	75.6	64.9		2.7	35
16		45D	2.06	0.82	0.67	0.59	0.54	0.48	0.41	0.37	0.08	12
		60D	5.88	2.12	1.72	1.53	1.4	1.24	1.06	0.96	0.15	14
	300	70D	18	7.1	5.8	5.1	4.7	4.1	3.6	3.2	0.3	16
	2DWELL	80D	34.4	14.1	11.4	10.1	9.3	8.2	7	6.4	0.6	19
		83D	34.9	14.4	12.7	10.5	9.8	8.7	7.3	6.7	0.6	19
		100D	37.1	15.6	13	11.2	10.2	9	7.6	7.1	0.6	22
		45D	1.15	0.65	0.52	0.4	0.33	0.29			0.08	10
		60D	1.76	0.94	0.76	0.68	0.62	0.55			0.1	12
	90	70D	5	3	2.5	2.2	2	1.8			0.3	14
	2DWELL	80D	22.8	8.6	8.6	8.6	8.6	8.6	7.4		0.6	16
		83D	23.4	8.9	8.9	8.9	8.9	8.9	7.7		0.6	16
		100D	28.1	11.2	10.6	10.2	9.6	9.2	8.3		0.8	19
		45D	1.15	0.7	0.62	0.49	0.41	0.33	0.25		0.07	10
		60D	2.33	1.18	0.96	0.85	0.78	0.69	0.59		0.12	12
		70D	5.5	2.9	2.4	2.1	1.9	1.7	1.5		0.3	14
		80D	25.4	9.1	9.1	9.1	9.1	8.3	7.2	6.5	0.6	16
	120	83D	27.1	9.4	9.4	9.4	9.4	8.6	7.5	6.8	0.6	16
	2DWELL	100D	29.3	10.6	9.8	9.7	9.7	9.1	8	7.2	0.7	19
20		110D	39.7	21.4	17.4	15.4	14.2	12.5			0.8	19
20		140D	73.8	38.7	31.4	27.8	25.5	22.6			1.2	14
		180D	144.1	76.8	62.4	55.2	50.7				2.3	16
		250D	410.8	235.1	190.9	169.1					4.5	19
		45D	1.35	0.63	0.54	0.43	0.36	0.29	0.2		0.06	10
		60D	2.44	1.07	0.87	0.77	0.71	0.63	0.54	0.48	0.11	12
		70D	5.9	2.7	2.2	1.9	1.8	1.6	1.3	1.2	0.2	14
		80D	28	9.5	9.5	9.5	8.7	7.7	6.6	6	0.5	16
	180	83D	29.2	9.8	9.8	9.7	9.1	8.1	6.9	6.3	0.6	16
	2DWELL	100D	31.2	10.4	10.2	10	9.4	8.6	7.3	6.5	0.7	19
		110D	42.9	19.7	16	14.2	13	11.5	9.9		0.7	19
		140D	79.5	35.6	28.9	25.6	23.5	20.8	17.8		1.1	22
		180D	191.7	90.7	73.7	65.3	59.9	53			2.4	35
		250D	453.9	218.8	177.7	157.4	144.4				4	40



No. of	Indexing	Mardal	Static Torque			Dynamic	Torque (k	gf-m)			Friction	Bearing
Stops	Angle	Model	Ts		Inde	exing Rota	iting Spee	d N (rpm)	)		Torque Tx	Dia.
S	θ		(kgf-m)	50	100	150	200	300	500	700	kgf•m	(mm)
		45D	1.45	0.59	0.48	0.37	0.3	0.27	0.18		0.06	10
		60D	2.49	0.99	0.8	0.71	0.65	0.58	0.5	0.45	0.11	12
		70D	6	2.5	2	1.8	1.6	1.5	1.2	1.1	0.2	14
		80D	29.1	9.7	9.7	8.9	8.2	7.2	6.2	5.6	0.5	16
	240	83D	31.5	9.9	9.8	9.1	8.5	7.5	6.6	6	0.6	16
	2DWELL	100D	34.1	10.4	10.3	10	9	8.2	7.1	6.5	0.7	19
		110D	44.2	18.4	14.9	13.2	12.1	10.7	9.2		0.7	19
		140D	81.8	33.1	26.9	23.8	21.8	19.3	16.6		1	22
		180D	197.1	84.4	68.6	60.7	55.7	49.3	42.3		2.2	35
		250D	636.1	291.2	236.6	209.5	192.1	170.1			4.5	40
		45D	1.5	0.56	0.45	0.34	0.3	0.26	0.17		0.06	10
		60D	2.5	0.96	0.78	0.69	0.63	0.56	0.48	0.43	0.1	12
		70D	6.1	2.4	2	1.7	1.6	1.4	1.2	1.1	0.2	14
20	270	80D	29.4	9.8	9.8	8.7	7.9	7	6	5.5	0.5	16
20	2DWELL	110D	44.6	17.8	14.5	12.8	11.8	10.4	8.9	8.1	0.7	19
		140D	82.5	32.1	26	23.1	21.2	18.7	16.1	14.5	1	22
		180D	198.6	81.8	66.4	58.8	54	47.8	41		2.2	35
		250D	643.9	232.8	229.7	203.4	186.6	165.2			4.4	40
		45D	1.52	0.54	0.43	0.33	0.29	0.25	0.16		0.06	10
		60D	2.51	0.93	0.76	0.67	0.61	0.54	0.47	0.42	0.1	12
		70D	6.1	2.3	1.9	1.7	1.5	1.4	1.2	1.1	0.2	14
		80D	29.7	9.8	9.5	8.4	7.7	6.8	5.9	5.3	0.5	16
	300	83D	32.3	10.2	10.1	9	8.1	7.1	6.5	6	0.6	16
	2DWELL	100D	35.6	10.8	10.3	9.4	8.6	7.5	6.9	6.3	0.7	19
		110D	44.8	17.3	14.1	12.5	11.4	10.1	8.7	7.8	0.7	19
		140D	83	31.2	25.3	22.4	20.6	18.2	15.6	14.1	1	22
		180D	199.8	79.5	64.6	57.2	52.4	46.4	39.8		2.2	35
		250D	649.6	275.3	223.6	198	181.6	160.8			4.4	40
		45D	0.5	0.31	0.21	0.19	0.15	0.13			0.06	10
		60D	0.94	0.49	0.4	0.35	0.32	0.29			0.09	10
		70D	2.7	1.6	1.3	1.1	1.1	0.9			0.2	12
		80D	24.5	8.9	8.9	8.9	8.9	8.9	8.2		0.6	16
24	90	83D	26.5	9.3	9.3	9.3	9.3	9.3	8.5		0.6	16
24	2DWELL	100D	28.5	10.3	9.8	9.8	9.8	9.5	8.8		0.7	19
		110D	35.5	16.8	16.8	15.9	14.6	12.9			0.8	19
		140D	48.3	27.9	22.7	20.1	18.4				1	22
		180D	110.9	65.7	53.3	47.2	43.3				2	30
		250D	246.7	151.7	123.3						3.4	40



No. of	Indexing	Model	Static Torque			Dynamic	Torque (k	(gf-m)			Friction Torque	Bearing Dia.
Stops	Angle	Model	Ts		Inde	exing Rota	iting Spee	d N (rpm)	)		Tx	
S	θ		(kgf-m)	50	100	150	200	300	500	700	kgf•m	(mm)
		45D	1.42	0.8	0.6	0.51	0.45	0.4			0.06	10
		60D	1.93	0.46	0.37	0.33	0.3	0.27			0.09	10
		70D	2.8	1.5	1.2	1.1	1	0.9			0.2	12
		80D	26.8	9.3	9.3	9.3	9.3	9.2	7.9	7.1	0.5	16
	120	83D	28.8	9.5	9.5	9.5	9.5	9.4	8.1	7.5	0.6	16
	2DWELL	100D	30.8	10.4	10.1	10	9.9	9.7	8.4	7.8	0.7	19
		110D	38.4	17.5	17.1	15.2	13.9	12.3			0.7	19
		140D	51.4	26.4	21.5	19	17.4	15.4			0.9	22
		180D	118.2	62.2	50.5	44.7	41				1.9	30
		250D	367.6	211.5	171.8	152.1	139.6				3.7	40
		45D	1.42	0.71	0.54	0.47	0.4	0.35			0.06	10
		60D	1.97	0.86	0.7	0.62	0.57	0.5	0.43	0.39	0.09	10
		70D	3	1.4	1.1	1	0.9	0.8	0.7		0.2	12
		80D	28.8	9.7	9.7	9.7	9.5	8.4	7.2	6.5	0.5	16
	180	83D	29.8	10.1	10.1	10.1	9.8	8.7	7.5	6.8	0.6	16
	2DWELL	100D	30.2	11	10.4	10.4	9.9	9.8	7.8	7.2	0.7	19
		110D	40.9	18.1	15.6	13.9	12.7	11.3	9.7		0.7	19
		140D	54	24	19.5	17.2	15.8	14			0.9	22
		180D	157.1	75.3	61.2	54.2	49.7	44			2	30
24		250D	395.5	194.3	157.8	139.7	128.2				3.4	40
2-7		45D	1.5	0.61	0.5	0.43	0.36	0.3			0.06	10
		60D	2	0.8	0.65	0.57	0.53	0.47	0.4	0.36	0.09	10
		70D	3	1.3	1	0.9	0.8	0.7	0.6	0.6	0.2	12
		80D	29.6	9.8	9.8	9.6	8.8	7.8	6.7	6.1	0.5	16
	240	83D	30.5	10.2	10.2	10.1	9.3	8.2	7.1	6.5	0.6	16
	2DWELL	100D	32.8	10.5	10.5	10.2	9.7	8.5	7.4	6.8	0.7	19
		110D	41.9	17.9	14.5	12.9	11.8	10.5	9	8.1	0.6	19
		140D	55	22.2	18	16	14.6	13	11.1		0.8	22
		180D	160.2	69.8	56.7	50.2	46	40.8	35		1.9	30
		250D	480.4	221.4	179.8	159.2	146.1	129.3			3.7	40
		45D	1.55	0.58	0.49	0.4	0.35	0.29			0.06	10
		60D	2.01	0.77	0.63	0.55	0.51	0.45	0.39	0.35	0.09	10
		70D	3.1	1.2	1	0.9	0.8	0.7	0.6	0.6	0.2	12
		80D	29.8	9.8	9.8	9.3	8.6	7.6	6.5	5.9	0.5	16
	270	83D	30.5	11.3	11.3	11	10.5	9.5	8.5	7.1	0.5	16
	2DWELL	100D	31.6	12.8	12.6	12.5	12.1	11.2	9.8	8.5	0.6	19
		110D	42.2	17.3	14.1	12.5	11.4	10.1	8.7	7.9	0.6	19
		140D	55.3	21.5	17.5	15.5	14.2	12.6	10.8		0.8	22
		180D	161.1	67.5	54.8	48.6	44.6	39.4	33.8		1.9	30
		250D	484.4	214.6	174.3	154.3	141.6	125.3			3.7	40



No.	Indexing	Model	Static Torque			Dynamic	Torque (k	gf-m)			Friction	Bearing
Stops	Angle	Model	Ts		Ind	exing Rota	iting Spee	d N (rpm)	)		Torque Tx	Dia.
S	θ		(kgf-m)	50	100	150	200	300	500	700	kgf•m	(mm)
		45D	1.55	0.52	0.47	0.38	0.33	0.27			0.06	10
		60D	2.01	0.75	0.61	0.54	0.49	0.44	0.37	0.34	0.09	10
		70D	3.1	1.2	1	0.9	0.8	0.7	0.6	0.5	0.2	12
		80D	30	9.9	9.9	9.1	8.3	7.4	6.3	5.7	0.5	16
24	300	83D	30.5	11.4	11.3	10.8	10	9.6	8.7	6.2	0.5	16
	2DWELL	100D	31.2	12.8	12.6	11.7	11.4	10.9	9.7	7.1	0.6	19
		110D	42.4	16.8	13.7	12.1	11.1	9.8	8.4	7.6	0.6	19
		140D	82.5	32.9	26.7	23.7	21.7	19.2	16.5	14.9	1	22
		180D	161.8	65.6	53.2	47.1	43.3	38.3	32.9		1.9	30
		250D	487.2	208.5	169.4	150	137.6	121.8			3.6	40
		45D	1.15	0.65	0.52	0.4	0.33	0.29	0.21		0.08	10
		60D	1.76	0.94	0.76	0.68	0.62	0.55	0.47		0.1	12
		70D	5	3	2.5	2.2	2	1.8	1.5		0.3	14
		80D	22.7	8.4	8.4	8.4	8.4	8.3	7.1	6.4	0.6	16
	90	83D	23.4	10.5	10.3	10.1	10	9.8	9.1	8.4	0.7	16
	3DWELL	100D	24	20.4	16.1	14	12.7	11.2			0.8	19
		110D	36.2	22.3	18.1	16.1	14.7	13.1			0.9	19
		140D	46	40.14	37.98	18.7	17.2	15.2			1.1	22
		180D	108.7	63.2	51.4	45.5	41.7				2.2	35
		250D	312.7	198.4	161.1	142.7					4.3	40
		45D	1.15	0.7	0.62	0.48	0.41	0.33	0.25		0.07	10
		60D	2.33	1.18	0.96	0.49	0.78	0.69	0.59	0.54	0.12	12
		70D	5.5	2.9	2.4	0.85	1.9	1.7			0.3	14
		80D	25.4	9.1	9.1	9.1	9.1	8.3	7.2		0.6	16
30	120	83D	25.9	11.1	11.1	11.1	11.1	10.3	9.2		0.7	16
30	3DWELL	100D	26.3	19.3	17.1	14.6	12.1	10.4	10.3		0.8	19
		110D	39.7	21.4	17.4	15.4	14.2	12.5	10.8		0.8	19
		140D	73.8	38.7	31.4	27.8	25.5	22.6	19.4		1.2	22
		180D	144.1	76.8	62.4	55.2	50.7	44.9			2.3	35
		250D	410.8	235.1	190.9	169.1	155.1				4.5	40
		45D	1.35	0.63	0.54	0.43	0.36	0.29	0.22		0.06	10
		60D	2.44	1.07	0.87	0.77	0.71	0.63	0.54	0.48	0.11	12
		70D	5.9	2.7	2.2	1.9	1.8	1.6	1.3		0.2	14
	180	80D	28	9.5	9.5	9.5	8.7	7.7	6.6	6	0.5	16
	2DWELL	83D	28.7	11.6	11.5	11.5	10.7	9.6	8.6	7.9	0.6	16
		100D	29.3	17.7	14.2	12.1	11.8	11.2	9.3	8.2	0.7	19
		110D	42.9	19.7	16	14.2	13	11.5	9.9	8.9	0.7	19
		140D	79.5	35.6	28.9	25.6	23.5	20.8	17.8	16.1	1.1	22
	180	180D	191.7	90.7	73.7	65.3	59.9	53	45.5		2.4	35
	3DWELL	250D	453.9	218.8	177.7	157.4	144.4	127.8			4	40



No. of	Indexing	Model	Static Torque			Dynamic	Torque (k	gf-m)			Friction Torque	Bearing Dia.
Stops	Angle O	Wodel	Ts (kgf-m)		Inde	exing Rota	ting Spee	d N (rpm)	)		Tx	(mm)
Ü	O		(Ngi iii)	50	100	150	200	300	500	700	kgf•m	(11111)
		45D	1.45	0.59	0.48	0.37	0.3	0.27	0.18		0.06	10
		60D	2.49	0.99	0.8	0.71	0.65	0.58	0.5	0.45	0.11	12
		70D	6	2.5	2	1.8	1.6	1.5	1.2	1.1	0.2	14
		80D	29.1	9.7	9.7	8.9	8.2	7.2	6.2	5.6	0.5	16
	240	83D	29.6	11.7	11.7	10.9	10.2	8.1	7.1	6.3	0.6	16
	3DWELL	100D	31.3	16.3	12.8	11.6	11.5	9.2	8.4	7.2	0.7	19
		110D	44.2	18.4	14.9	13.2	12.1	10.7	9.2	8.3	0.7	19
		140D	81.8	33.1	26.9	23.8	21.8	19.3	16.6	15	1	22
		180D	197.1	84.4	68.6	60.7	55.7	49.3	42.3	38.2	2.2	35
		250D	636.1	291.2	236.6	209.5	192.1	170.1	146		4.5	40
		45D	1.5	0.56	0.45	0.34	0.3	0.26	0.17		0.06	10
		60D	2.5	0.96	0.78	0.69	0.63	0.56	0.48	0.43	0.1	12
		70D	6.1	2.4	2	1.7	1.6	1.4	1.2	1.1	0.2	14
		80D	29.4	9.8	9.8	8.7	7.9	7	6	5.5	0.5	16
30	270	83D	30.2	11.8	11.8	10.2	9.6	8.2	6.8	6.1	0.6	16
	3DWELL	100D	32.4	15.6	12.3	11.8	11.5	9.4	8.6	7	0.7	19
		110D	44.6	17.8	14.5	12.8	11.8	10.4	8.9	8.1	0.7	19
		140D	82.5	32.1	26	23.1	21.2	18.7	16.1	14.5	1	22
		180D	198.6	81.8	66.4	58.8	54	47.8	41	37.1	2.2	35
		250D	643.9	282.8	229.7	203.4	186.6	165.2	141.8		4.4	40
		45D	1.52	0.54	0.43	0.33	0.29	0.25	0.16		0.06	10
		60D	2.51	0.93	0.76	0.67	0.61	0.54	0.47	0.42	0.1	12
		70D	6.1	2.3	1.9	1.7	1.5	1.4	1.2	1.1	0.2	14
		80D	29.7	9.8	9.5	8.4	7.7	6.8	5.9	5.3	0.5	16
	300	83D	30.7	11.8	11.5	10	9.1	8.4	7.1	6.4	0.6	16
	3DWELL	100D	32.8	15.4	12.1	11.2	10.9	10	8.6	7.4	0.7	19
		110D	44.8	17.3	14.1	12.5	11.4	10.1	8.7	7.8	0.7	19
		140D	83	31.2	25.3	22.4	20.6	18.2	15.6	14.1	1	22
		180D	199.8	79.5	64.6	57.2	52.4	46.4	39.8	36	2.2	35
		250D	649.6	275.3	223.6	198	181.6	160.8	138		4.4	40
	120	80D	23.4	8.7	8.7	8.7	8.2	7.3			0.6	19
	4DWELL	83D	23.7	11.8	11.6	11	10.2	9.4			0.6	19
	.5.0222	100D	24.5	12.3	12.2	11.3	10.3	9.8			0.7	19
32		110D	38.1	12.8	12.8	12.8	12.8	12.5			0.7	16
	120	140D	48.1	21.1	20.6	18.3	16.8	14.8			0.8	19
	2DWELL	180D	68.5	35.2	28.6	25.3	23.2				1.4	22
		250D	228.5	128.1	104	92.1					2.7	30



No. of	Indexing	Mardal	Static Torque	que						Friction	Bearing	
Stops	Angle	Model	Ts (kgf m)		Ind	exing Rota	iting Spee	d N (rpm)	)		Torque Tx	Dia.
S	θ		(kgf-m)	50	100	150	200	300	500	700	kgf•m	(mm)
	180 4DWELL	80D	31.4	15.6	12.7	11.3	10.3	9.1	7.8		0.6	19
		83D	33.7	12.9	11.6	10.8	9.5	8.5	7.4		0.6	12
		100D	35.4	12.9	12.8	12.8	12.7	11.4	8.9		0.6	14
	180	110D	39.6	13.1	13.1	13.1	12.7	11.3	9.7		0.6	16
	2DWELL	140D	49.4	21.4	18.5	16.5	15	13.3	11.4		0.8	19
		180D	104.5	49.6	40.3	35.6	32.7	29			1.5	22
		250D	295.1	149.1	121.1	107.3	98.4				2.8	30
	240 4DWELL	80D	33.4	14.8	12	10.6	9.8	8.6	7.4	6.7	0.6	19
		83D	35.2	12.6	11.2	10.4	9.1	9.1	7.1	6	0.6	12
		100D	38.1	12.9	12.8	12.7	11.6	9.5	8.9	8.1	0.6	14
	240	110D	40.2	13.2	13.2	12.8	11.7	10.4	8.9	8.1	0.6	16
	2DWELL	140D	49.9	21	17.1	15.1	13.9	12.3	10.5		0.7	19
		180D	105.7	45.7	37.1	32.9	30.2	26.7	22.9		1.5	22
32		250D	299.7	137.9	112	99.2	91	80.5			2.7	30
	270 4DWELL	80D	33.9	14.4	11.7	10.4	9.5	8.4	7.2	6.5	0.6	19
		83D	35.7	12.3	11.2	10.2	9.3	8.2	7.1	6	0.6	12
		100D	38.3	12.9	12.8	12.1	11.2	9.6	8.6	7.8	0.6	14
	270	110D	40.4	13.2	13.2	12.4	11.4	10.1	8.6	7.8	0.6	16
	2DWELL	140D	50.1	20.3	16.5	14.6	13.4	11.9	10.2	9.2	0.7	19
		180D	106	44.2	35.9	31.8	29.2	25.8	22.1		1.4	22
		250D	301	133.4	108.3	95.9	88	77.9			2.7	30
	300 4DWELL	80D	34.4	14.1	11.4	10.1	9.3	8.2	7	6.4	0.6	19
		83D	36.2	12.2	11	9.8	9.1	8.1	6.9	5.8	0.6	12
		100D	38.5	12.7	12.6	11.9	10.8	10.3	7.4	6.6	0.6	14
	300	110D	40.5	13.2	13.2	12	11	9.8	8.4	7.6	0.6	16
	2DWELL	140D	50.2	19.7	16	14.2	13	11.5	9.9	8.9	0.7	19
		180D	106.3	42.9	34.8	40.8	28.3	25	21.5		1.4	22
		250D	302	129.4	105.1	93.1	85.4	75.6			2.7	30
		70D	2.8	1.5	1.2	1.1	1	0.9			0.2	12
		80D	26.8	9.3	9.3	9.3	9.3	9.2	7.9		0.5	16
	120	83D	28.1	11.3	11.3	11.3	11.3	11.2	9.9		0.6	16
36	3DWELL	100D	36.7	15.5	15.1	13.2	12.6	11.4			0.7	19
		140D	51.4	26.4	21.5	19	17.4	15.4			0.9	22
		180D	118.2	62.2	50.5	44.7	41	36.3			1.9	30
		250D	367.6	211.5	171.8	152.1	139.6				3.7	40



No. of	Indexing	Model	Static Torque			Dynamic	Torque (k	(gf-m)			Friction Torque	Bearing Dia.
Stops	Angle O	woder	Ts (kgf-m)		Inde	exing Rota	iting Spee	d N (rpm)	)		Tx	(mm)
3	O		(KgI-III)	50	100	150	200	300	500	700	kgf•m	(111111)
		70D	3	1.4	1.1	1	0.9	0.8			0.2	12
		80D	28.8	9.7	9.7	9.7	9.5	8.4	7.2	6.5	0.5	16
		83D	30.2	12.7	12.7	12.7	12	11	9.1	6.8	0.6	16
	180	100D	38.6	16.1	15.3	13.6	12.3	11.2			0.7	19
	3DWELL	110D	40.9	18.1	15.6	13.9	12.7	11.3			0.7	19
		140D	54	24	19.5	17.2	15.8	14	37.7		0.9	22
		180D	157.1	75.3	61.2	54.2	49.7	44			2	30
		250D	395.5	194.3	157.8	139.7	128.2	113.5			3.4	40
		70D	3	1.3	1	0.9	0.8	0.7	0.6		0.2	12
		80D	29.6	9.8	9.8	9.6	8.8	7.8	6.7	6.1	0.5	16
		83D	31.7	12.8	12.8	10.6	9.4	8.5	7.5		0.5	16
	240	100D	40.1	16	14.1	11.3	10.5	9.6	8.4		0.6	19
	3DWELL	110D	41.9	17.9	14.5	12.9	11.8	10.5	9		0.6	19
		140D	55	22.2	18	16	14.6	13	11.1		0.8	22
		180D	160.2	69.8	56.7	50.2	46	40.8	35	31.6	1.9	30
36		250D	480.4	221.4	179.8	159.2	146.1	129.3	111		3.7	40
		70D	3.1	1.2	1	0.9	0.8	0.7	0.6		0.2	12
		80D	29.8	9.8	9.8	9.3	8.6	7.6	6.5	5.9	0.5	16
		83D	31.9	12.8	12.8	10.3	9.2	8.3	7.4	5.7	0.5	16
	270	100D	40.3	16	13.8	11	10.3	9.3	8.3		0.6	19
	3DWELL	110D	42.2	17.3	14.1	12.5	11.4	10.1	8.7		0.6	19
		140D	55.3	21.5	17.5	15.5	14.2	12.6	10.8		0.8	22
		180D	161.1	67.5	54.8	48.6	44.6	39.4	33.8	30.6	1.9	30
		250D	484.4	214.6	174.3	154.3	141.6	125.3	107.5		3.7	40
		70D	3.1	1.2	1	0.9	0.8	0.7	0.6	0.5	0.2	12
		80D	30	9.9	9.9	9.1	8.3	8	6.3	5.7	0.5	16
		83D	32.1	12.9	12.9	10.1	9	8.4	7.3	6.1	0.5	16
	300	100D	40.5	15.7	12.4	11.2	10.3	9	8.2	7.1	0.6	19
	3DWELL	110D	42.4	16.8	13.7	12.1	11.1	9.2	8.4	7.6	0.6	19
		140D	82.5	32.9	26.7	23.7	21.7	19.2	16.5	14.9	1	22
		180D	161.8	65.6	53.2	47.1	43.3	38.3	32.9	29.7	1.9	30
		250D	487.2	208.5	169.4	150	137.6	121.8	104.5		3.6	40
		70D	5.5	2.9	2.4	2.1	1.9	1.7			0.3	14
		80D	25.4	9.1	9.1	9.1	9.1	8.3	7.2		0.6	16
		83D	27.5	10.6	10.6	10.6	10.6	9.1			0.6	16
40	120	100D	36.9	19.2	15.6	13.7	13.1	9.4			0.7	19
1 +0	4DWELL	110D	39.7	21.4	17.4	15.4	14.2	9.7			0.8	19
		140D	73.8	38.7	31.4	27.8	25.5				1.2	22
		180D	144.1	76.8	62.4	55.2	50.7	44.9			2.3	35
		250D	410.8	235.1	190.9	169.1	155.1				4.5	40



No.	No. of Stops Angle Model Ts					Dynamic	Torque (k	(gf-m)			Friction	Bearing
Stops	Angle	Model			Inde	exing Rota	iting Spee	d N (rpm)	)		Torque Tx	Dia.
S	θ		(kgf-m)	50	100	150	200	300	500	700	kgf•m	(mm)
		70D	5.9	2.7	2.2	1.9	1.8	1.6	1.3		0.2	14
		80D	28	9.5	9.5	9.5	8.7	7.7	6.6	6	0.5	16
		83D	30.1	11.4	11.3	11.2	10.2	8.9	7.7	7.2	0.5	16
	180	100D	38.4	17.6	15.2	13.1	11.8	10.9			0.6	19
	4DWELL	110D	42.9	19.7	16	14.2	13	11.5			0.7	19
		140D	79.5	35.6	28.9	25.6	23.5	20.8			1.1	22
		180D	191.7	90.7	73.7	65.3	59.9	53	45.5		2.4	35
		250D	453.9	218.8	177.7	157.4	144.4	127.8			4	40
		70D	6	2.5	2	1.8	1.6	1.5	1.2		0.2	14
		80D	29.1	9.7	9.7	8.9	8.2	7.2	6.2	5.6	0.5	16
		83D	32.1	11.5	11.4	11.2	9.7	8.6	7.5	6.9	0.5	16
	240	100D	41.7	17.2	14.8	12.7	11.5	10.3	8.6		0.6	19
	4DWELL	110D	44.2	18.4	14.9	13.2	12.1	10.7	9.2		0.7	22
		140D	81.8	33.1	26.9	23.8	21.8	19.3			1	35
		180D	197.1	84.4	68.6	60.7	55.7	49.3	42.3	38.2	2.2	40
40		250D	636.1	291.2	236.6	209.5	192.1	170.1	146		4.5	60
10		70D	6.1	2.4	2	1.7	1.6	1.4	1.2	1.1	0.2	14
		80D	29.4	9.8	9.8	8.7	7.9	7	6	5.5	0.5	16
		83D	32.6	11.6	11.5	11	9.4	8.5	7.3	6.7	0.5	16
	270	100D	42.1	16.8	13.9	12.5	11.2	10.1	8.6		0.6	19
	4DWELL	110D	44.6	17.8	14.5	12.8	11.8	10.4	8.9		0.7	19
		140D	82.5	32.1	26	23.1	21.2	18.7	16.1		1	22
		180D	198.6	81.8	66.4	58.8	54	47.8	41	37.1	2.2	35
		250D	643.9	282.8	229.7	203.4	186.6	165.2	141.8		4.4	40
		70D	6.1	2.3	1.9	1.7	1.5	1.4	1.2	1.1	0.2	14
		80D	29.7	9.8	9.5	8.4	7.7	6.8	5.9	5.3	0.5	16
		83D	32.6	11.6	11.4	10.8	9.2	8.2	7.2	6.4	0.5	16
	300	100D	42.1	16.5	13.7	12.3	11	9.7	8.3		0.6	19
	4DWELL	110D	44.8	17.3	14.1	12.5	11.4	10.1	8.7		0.7	19
		140D	83	31.2	25.3	22.4	20.6	18.2	15.6		1	22
		180D	199.8	79.5	64.6	57.2	52.4	46.4	39.8	36	2.2	35
		250D	649.6	275.3	223.6	198	181.6	160.8	138		4.4	40
		70D	2.8	1.5	1.2	1.1	1	0.9			0.2	12
	120	80D	26.8	9.3	9.3	9.3	9.3	9.2	7.9		0.5	16
	4DWELL	83D	28.3	9.6	9.6	9.5	9.5	9.4	8.9		0.5	16
48		100D	36.2	11.3	11.3	11	11	10.8			0.6	19
		110D	38.1	12.8	12.8	12.8	12.8	12.5			0.7	19
	120	140D	48.1	21.1	20.6	18.3	16.8	14.8			0.8	22
	3DWELL	180D	118.2	62.2	50.5	44.7	41	36.3			1.9	30
		250D	367.6	211.5	171.8	152.1	139.6				3.7	45



No.	Indexing	Model	Static Torque			Dynamic	Torque (k	gf-m)			Friction Torque	Bearing Dia.
Stops	Angle O	woder	Ts (kgf-m)		Inde	exing Rota	iting Spee	d N (rpm)	)		Tx	(mm)
3	O		(kgi-iii)	50	100	150	200	300	500	700	kgf•m	(111111)
		70D	3	1.4	1.1	1	0.9	0.8			0.2	12
	180	80D	28.8	9.7	9.7	9.7	9.5	8.4	7.2	6.5	0.5	16
	4DWELL	83D	29.7	10.1	10.1	9.8	9.8	9.7	8.5	7.8	0.5	16
		100D	37.2	11.6	11.6	11.2	11.2	10.6	9.2		0.6	19
		110D	39.6	13.1	13.1	13.1	12.7	11.3	9.7		0.6	19
	180	140D	49.4	21.4	18.5	16.4	15	13.3			0.8	22
	3DWELL	180D	157.1	75.3	61.2	54.2	49.7	44	37.7		2	22
		250D	395.5	194.3	157.8	139.7	128.2	113.5			3.4	30
		70D	3	1.3	1	0.9	0.8	0.7	0.6		0.2	12
	240	80D	29.6	9.8	9.8	9.6	8.8	7.8	6.7	6.1	0.5	16
	4DWELL	83D	31.5	10.2	10.2	9.9	9.9	8.5	7.9	7.3	0.5	16
		100D	38.6	11.7	11.7	11	10.8	9.9	8.6		0.6	19
		110D	40.2	13.2	13.2	12.8	11.7	10.4	8.9		0.6	19
	240	140D	49.9	21	17.1	15.1	13.9	12.3	10.5		0.7	22
	3DWELL	180D	160.2	69.8	56.7	50.2	46	40.8	35	31.6	1.9	22
48		250D	480.4	221.4	179.8	159.2	146.1	129.3	111		1.9	22
40		70D	3.1	1.2	1	0.9	0.8	0.7	0.6		0.2	12
	270	80D	29.8	9.8	9.8	9.3	8.6	7.6	6.5	5.9	0.5	16
	4DWELL	83D	32	10.2	10.2	9.9	9.7	8.3	7.7	7.1	0.5	16
		100D	38.7	11.7	11.7	11	10.5	9.7	8.4	8.2	0.6	19
		110D	40.4	13.2	13.2	12.4	11.4	10.1	8.6	7.8	0.6	19
	270	140D	50.1	20.3	16.5	14.6	13.4	11.9	10.2		0.7	22
	3DWELL	180D	161.1	67.5	54.8	48.6	44.6	39.4	33.8	30.6	1.9	22
		250D	484.4	214.6	174.3	154.3	141.6	125.3	107.5		3.7	30
		70D	3.1	1.2	1	0.9	0.8	0.7	0.6		0.2	12
	300	80D	30	9.9	9.9	9.1	8.3	7.4	6.3	5.7	0.5	16
	4DWELL	83D	32.5	10.3	10.3	9.7	9.5	8.1	7.5	6.9	0.5	16
		100D	38.9	11.7	11.7	10.8	10.3	9.6	8.2	8	0.6	19
		110D	40.5	13.2	13.2	12	11	9.8	8.4	7.6	0.6	19
	300	140D	50.2	19.7	16	14.2	13	11.5	9.9		0.7	22
	3DWELL	180D	161.8	65.6	53.2	47.1	43.3	38.3	32.9	29.7	1.9	22
		250D	467.2	208.5	169.4	150	137.6	121.8	104.5		3.6	30

### **CAMDEX** drives



### P Series

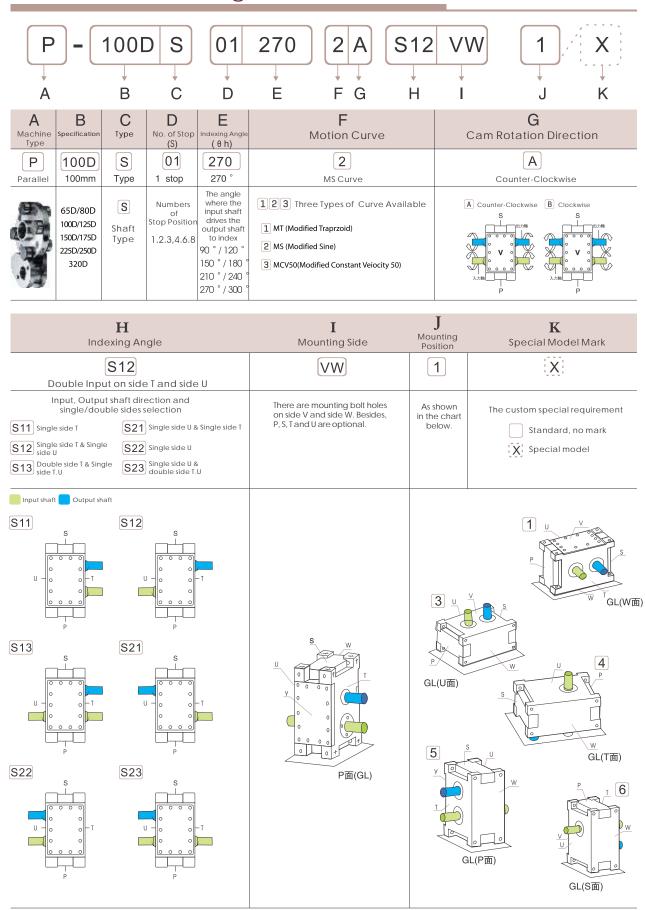
P065 / P080 / P100 / P125 / P150 / P175 P225 / P250 / P320

#### Product Features

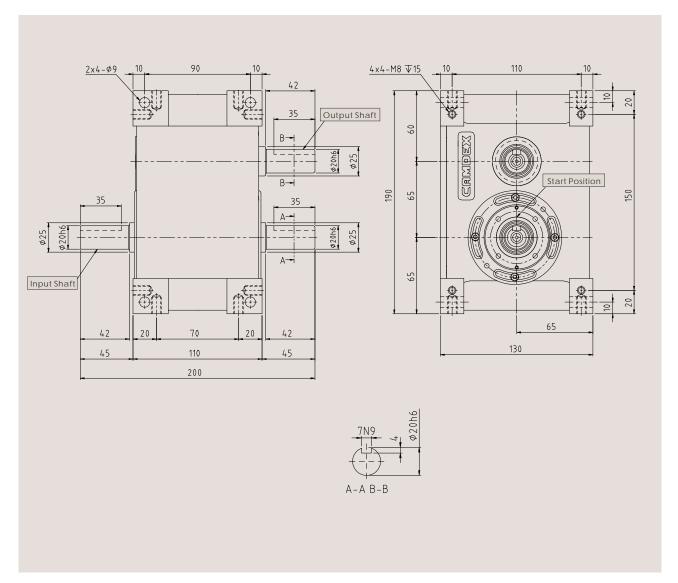
Product Features: It contains two plate type cams and the turret driven by the cam followers. This index drive has parallel co-shaft cams, whose rotation drives the cam follower turret to perform indexing. It is most suitable for driving large pitch distance conveyor or for longer dwell indexing. 3-parallel cam type is available for heavier load capacity, suitable for longer pitch distance transportation at a higher speed. The dwell period is also longer than that of 2-parallel cam type.



### Model Code Designation:

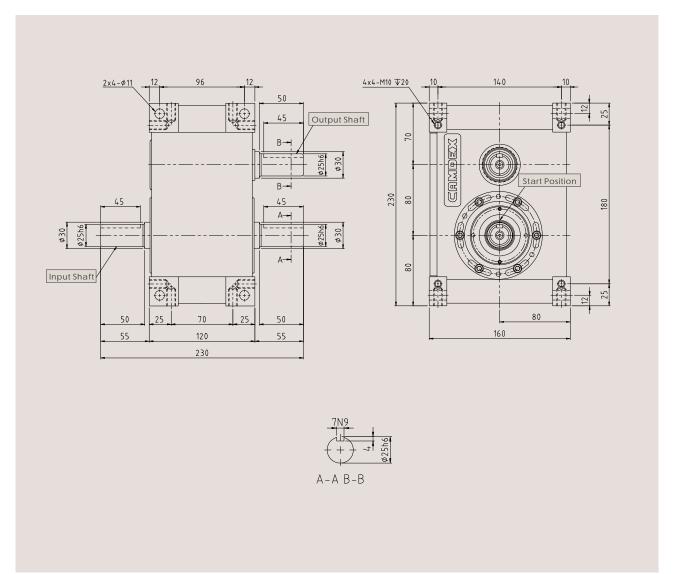


## P065 P Series



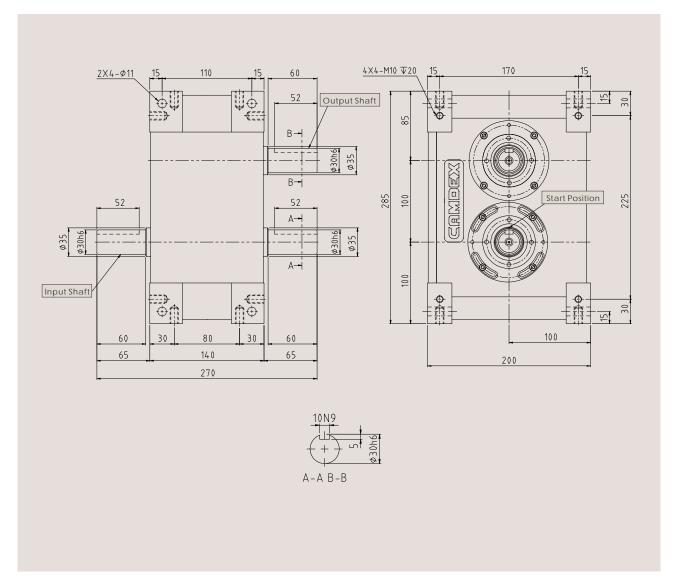
Properties	Symbol	Unit	Value
Allowable Output shaft radial load	P1	kgf	250
Allowable Output shaft axial load	P2	kgf	160
Allowable Output shaft torque	Ts	kgf-m	refer to torque chart
Output shaft moment of deflection	K1	kgf-m/rad	$9.2 \times 10^{2}$
Allowable Input shaft radial load	P4	kgf	250
Allowable Input shaft axial load	P5	kgf	160
Allowable Input shaft torque	P6	kgf-m	11
Input shaft moment of deflection	K2	kgf-m/rad	9.2×10 <sup>2</sup>
1Dwell indexing accuracy		sec.	±60
2Dwell indexing accuracy		sec.	±120
Repeat positioning accuracy		sec.	60
Weight		kg	15

## P080 P Series



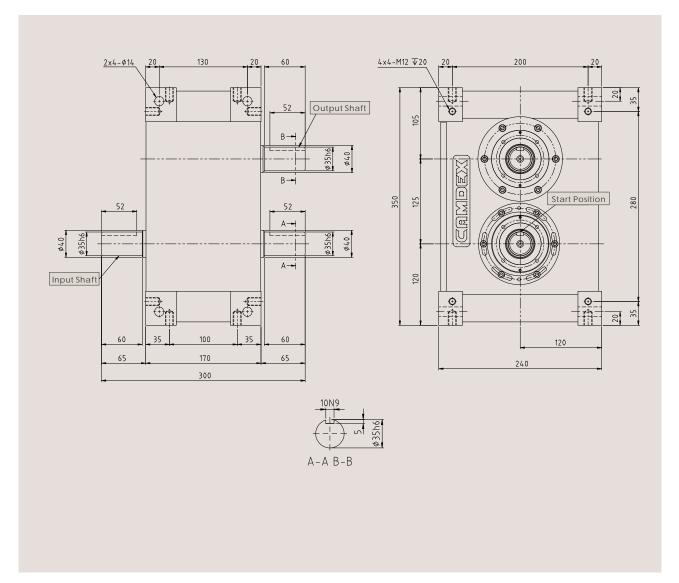
Properties	Symbol	Unit	Value
Allowable Output shaft radial load	P1	kgf	360
Allowable Output shaft axial load	P2	kgf	250
Allowable Output shaft torque	Ts	kgf-m	refer to torque chart
Output shaft moment of deflection	K1	kgf-m/rad	1.85×10 <sup>3</sup>
Allowable Input shaft radial load	P4	kgf	360
Allowable Input shaft axial load	P5	kgf	250
Allowable Input shaft torque	P6	kgf-m	25
Input shaft moment of deflection	K2	kgf-m/rad	1.85×10³
1Dwell indexing accuracy		sec.	±60
2Dwell indexing accuracy		sec.	±120
Repeat positioning accuracy		sec.	60
Weight		kg	20

## P100 P Series



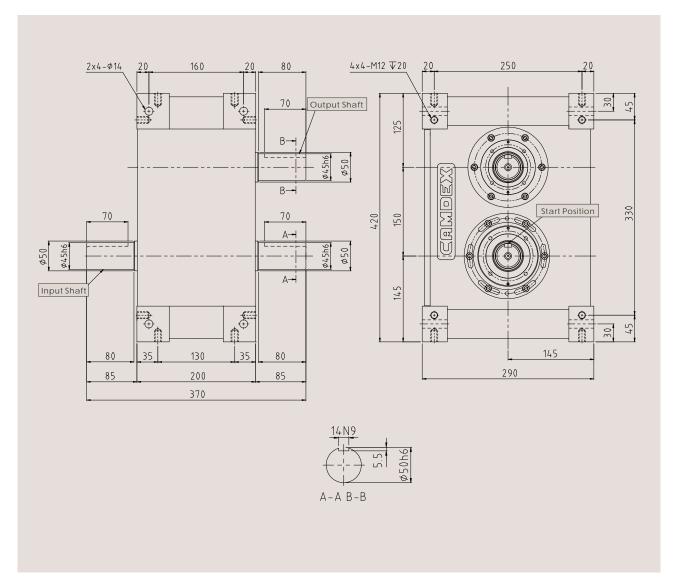
Properties	Symbol	Unit	Value
Allowable Output shaft radial load	P1	kgf	480
Allowable Output shaft axial load	P2	kgf	400
Allowable Output shaft torque	Ts	kgf-m	refer to torque chart
Output shaft moment of deflection	K1	kgf-m/rad	3.26×10 <sup>3</sup>
Allowable Input shaft radial load	P4	kgf	480
Allowable Input shaft axial load	P5	kgf	400
Allowable Input shaft torque	P6	kgf-m	40
Input shaft moment of deflection	K2	kgf-m/rad	3.26×10 <sup>3</sup>
1Dwell indexing accuracy		sec.	±60
2Dwell indexing accuracy		sec.	±120
Repeat positioning accuracy		sec.	60
Weight		kg	38

# P125 P Series



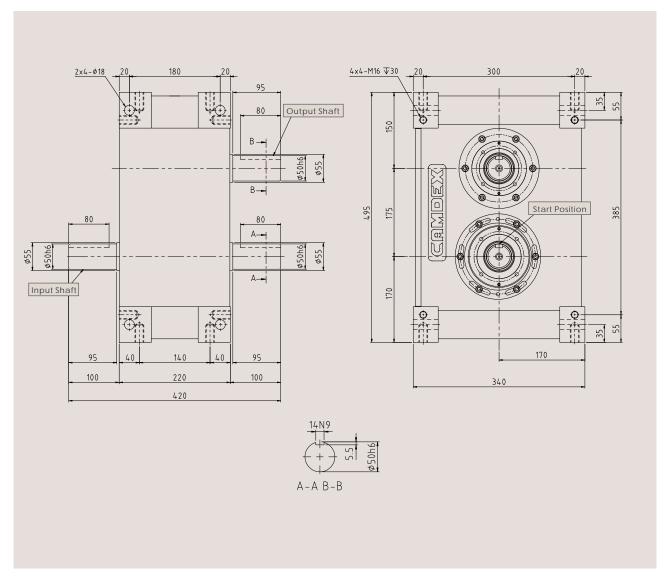
Properties	Symbol	Unit	Value
Allowable Output shaft radial load	P1	kgf	520
Allowable Output shaft axial load	P2	kgf	630
Allowable Output shaft torque	Ts	kgf-m	refer to torque chart
Output shaft moment of deflection	K1	kgf-m/rad	5.03×10³
Allowable Input shaft radial load	P4	kgf	520
Allowable Input shaft axial load	P5	kgf	630
Allowable Input shaft torque	P6	kgf-m	65
Input shaft moment of deflection	K2	kgf-m/rad	5.03×10³
1Dwell indexing accuracy		sec.	±60
2Dwell indexing accuracy		sec.	±120
Repeat positioning accuracy		sec.	60
Weight		kg	65

## P150 P Series



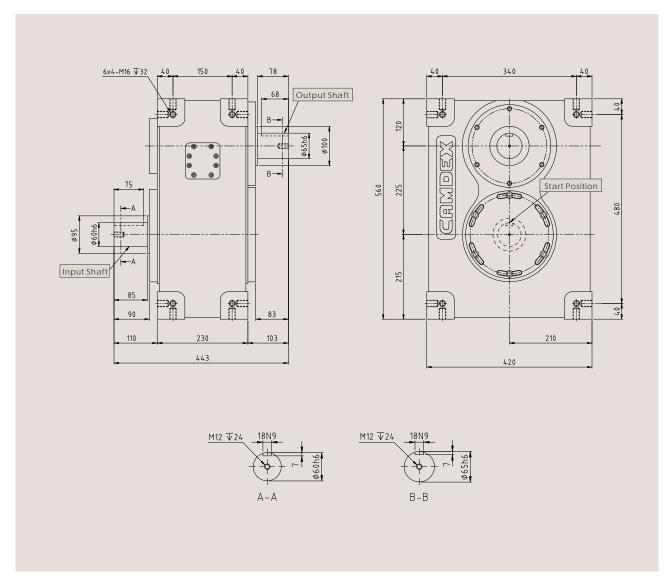
Properties	Symbol	Unit	Value
Allowable Output shaft radial load	P1	kgf	750
Allowable Output shaft axial load	P2	kgf	860
Allowable Output shaft torque	Ts	kgf-m	refer to torque chart
Output shaft moment of deflection	K1	kgf-m/rad	1.8×10 <sup>4</sup>
Allowable Input shaft radial load	P4	kgf	750
Allowable Input shaft axial load	P5	kgf	280
Allowable Input shaft torque	P6	kgf-m	135
Input shaft moment of deflection	K2	kgf-m/rad	1.8×10 <sup>4</sup>
1Dwell indexing accuracy		sec.	±60
2Dwell indexing accuracy		sec.	±120
Repeat positioning accuracy		sec.	60
Weight		kg	87

## P175 P Series



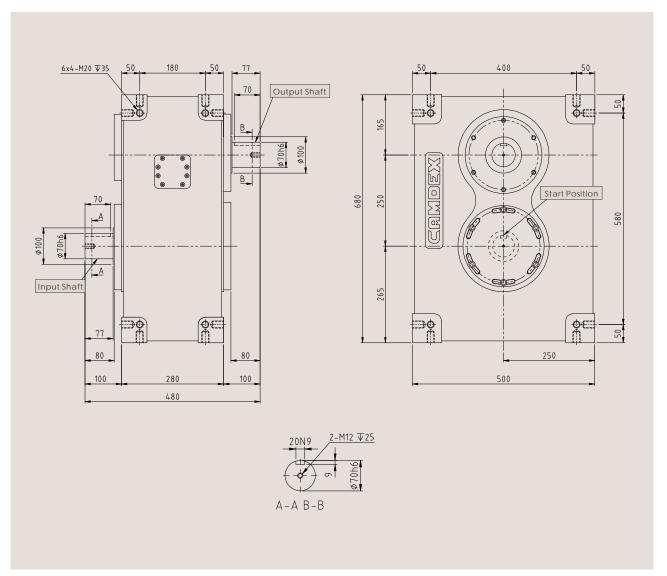
Properties	Symbol	Unit	Value
Allowable Output shaft radial load	P1	kgf	920
Allowable Output shaft axial load	P2	kgf	1000
Allowable Output shaft torque	Ts	kgf-m	refer to torque chart
Output shaft moment of deflection	K1	kgf-m/rad	1.68×10⁴
Allowable Input shaft radial load	P4	kgf	920
Allowable Input shaft axial load	P5	kgf	1000
Allowable Input shaft torque	P6	kgf-m	185
Input shaft moment of deflection	K2	kgf-m/rad	1.68×10 <sup>4</sup>
1Dwell indexing accuracy		sec.	±60
2Dwell indexing accuracy		sec.	±120
Repeat positioning accuracy		sec.	60
Weight		kg	127

# P225 P Series



Properties	Symbol	Unit	Value
Allowable Output shaft radial load	P1	kgf	1435
Allowable Output shaft axial load	P2	kgf	1470
Allowable Output shaft torque	Ts	kgf-m	refer to torque chart
Output shaft moment of deflection	K1	kgf-m/rad	4.31×10 <sup>4</sup>
Allowable Input shaft radial load	P4	kgf	1435
Allowable Input shaft axial load	P5	kgf	2150
Allowable Input shaft torque	P6	kgf-m	410
Input shaft moment of deflection	K2	kgf-m/rad	4.31×10 <sup>4</sup>
1Dwell indexing accuracy		sec.	±60
2Dwell indexing accuracy		sec.	±120
Repeat positioning accuracy		sec.	60
Weight		kg	220

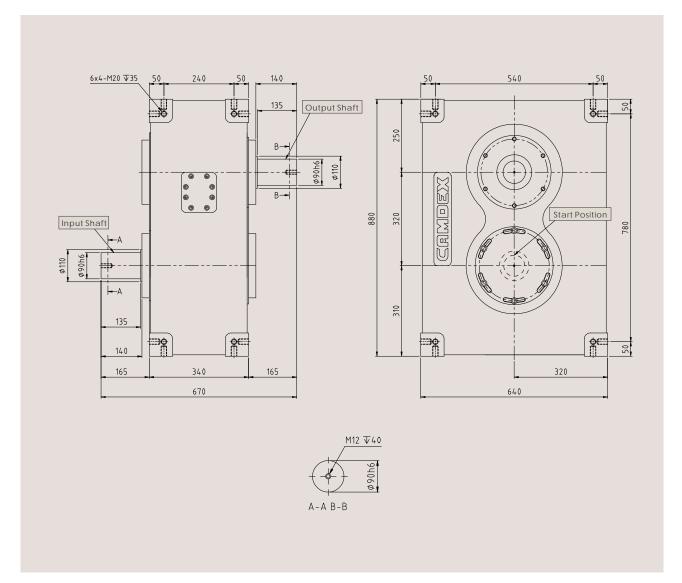
## P250 P Series



### Technical Data

Properties	Symbol	Unit	Val値
Allowable Output shaft radial load	P1	kgf	1550
Allowable Output shaft axial load	P2	kgf	1560
Allowable Output shaft torque	Ts	kgf-m	refer to torque chart
Output shaft moment of deflection	K1	kgf-m/rad	5.37×10 <sup>4</sup>
Allowable Input shaft radial load	P4	kgf	1550
Allowable Input shaft axial load	P5	kgf	2400
Allowable Input shaft torque	P6	kgf-m	500
Input shaft moment of deflection	K2	kgf-m/rad	5.37×10 <sup>4</sup>
1Dwell indexing accuracy		sec.	±60
2Dwell indexing accuracy		sec.	±120
Repeat positioning accuracy		sec.	60
Weight		kg	388

# P320 P Series



### Technical Data

Properties	Symbol	Unit	Value
Allowable Output shaft radial load	P1	kgf	1720
Allowable Output shaft axial load	P2	kgf	1775
Allowable Output shaft torque	Ts	kgf-m	refer to torque chart
Output shaft moment of deflection	K1	kgf-m/rad	5.8×10 <sup>4</sup>
Allowable Input shaft radial load	P4	kgf	1690
Allowable Input shaft axial load	P5	kgf	2670
Allowable Input shaft torque	P6	kgf-m	580
Input shaft moment of deflection	K2	kgf-m/rad	5.8×10 <sup>4</sup>
1Dwell indexing accuracy		sec.	±60
2Dwell indexing accuracy		sec.	±120
Repeat positioning accuracy		sec.	60
Weight		kg	750



No. of	Indexing	C	Madal	Static Torque		Dyn	amic Torq	ue (kgf-n	າ)		Friction Torque	Bearing Dia.
Stops S	Angle O	Curve	Model	Ts (kgf-m)		Indexing	g Rotating	Speed N	(rpm)		·	
O	O			(9)	50	75	100	150	200	300		
			P050	3.68	1.35	1.20	1.10	0.97	0.89	0.79	0.13	16
			P065	7.81	3.13	2.77	2.54	2.23	2.06	1.83	0.26	16
			P080	15.06	6.28	5.56	5.10	4.51	4.14	3.66	0.40	22
			P100	25.90	10.58	9.37	8.59	7.61	6.98	6.18	0.60	26
	270	MCV50	P125	38.94	17.79	15.75	14.45	12.79	11.74	10.39	0.83	35
	270	IVICV30	P150	58.35	26.24	23.24	21.32	18.87	17.31	15.33	1.22	40
			P175	91.50	41.38	36.64	33.61	29.76	27.30		1.69	45
			P225	256.91	125.61	101.34	95.60	87.52	81.25		3.60	60
			P250	339.24	140.93	124.79	114.47	101.36	92.98		4.45	80
			P320	611.11	253.88	224.81	206.22	182.60			8.80	100
			P050	3.26	1.16	1.03	0.94	0.83	0.76	0.68	0.15	16
		MS	P065	7.04	2.73	2.42	2.22	1.96	1.80	1.59	0.30	16
		IVIS	P080	13.56	5.47	4.84	4.44	3.93	3.61	3.19	0.46	22
			P100	23.31	9.23	8.17	7.49	6.63	6.08	5.39	0.68	26
			P050	3.89	1.38	1.23	1.12	0.99	0.91	0.81	0.12	16
		MCV50	P065	8.24	3.20	2.83	2.60	2.30	2.11	1.87	0.24	16
	300		P080	16.14	6.52	5.77	5.29	4.68	4.30	3.80	0.38	22
	300		P100	25.90	10.25	9.08	8.33	7.37	6.76	5.99	0.57	26
1			P125	40.71	18.02	15.96	14.64	12.96	11.89	10.53	0.78	35
1		IVICV5U	P150	61.66	26.87	23.79	21.82	19.32	17.72	15.69	1.15	40
			P175	97.50	42.73	37.83	34.70	30.73	28.19	24.96	1.60	45
			P225	278.41	128.56	104.41	97.25	90.20	83.51		3.71	60
			P250	356.68	143.57	127.13	116.61	103.26	94.72		4.23	80
			P320	637.68	256.68	227.28	208.49	184.61	169.34		8.40	100
			P050	3.26	1.13	1.00	0.91	0.81	0.74	0.66	0.14	16
		MS	P065	7.04	2.65	2.35	2.15	1.91	1.75	1.55	0.28	16
		1013	P080	13.56	5.32	4.71	4.32	3.82	3.51	3.10	0.43	22
			P100	23.31	8.97	7.94	7.28	6.45	5.91	5.24	0.65	26
			P050	3.89	1.35	1.19	1.09	0.97	0.89	0.78	0.12	16
		NACVEO	P065	8.24	3.11	2.75	2.52	2.23	2.05	1.81	0.23	16
	220	MCV50	P080	16.14	6.33	5.61	5.14	4.55	4.18	3.70	0.36	22
	330		P100	29.60	11.39	10.08	9.25	8.19	7.51	6.65	0.53	26
		P125	40.71	17.51	15.51	14.22	12.59	11.55	10.23	0.80	35	
		P150	60.56	25.64	22.71	20.83	18.44	16.92	14.98	1.18	40	
		P175	93.75	39.92	35.35	32.43	28.71	26.34	23.32	1.64	45	
		MCV25	P225	278.41	126.71	101.69	94.50	86.73	81.20	76.51	3.70	60
			P250	356.68	139.52	123.54	113.33	100.35	92.05	81.51	4.32	80
			P320	627.05	245.29	217.19	199.23	176.41	161.83		8.58	100



No. of	Indexing	0	NA - d - l	Static Torque		Dyr	namic Torc	ηue ( <b>kgf-r</b>	n)		Friction Torque	Bearing Dia.
Stops	Angle	Curve	Model	Ts		Indexin	g Rotating	Speed N	(rpm)		Tx	
S	θ			(kgf-m)	50	75	100	150	200	300	kgf•m	(mm)
			P050	3.68	1.37	1.22	1.12	0.99	0.90	0.80	0.12	14
			P065	8.24	3.40	3.01	2.76	2.45	2.24	1.99	0.24	16
			P080	15.06	6.08	5.38	4.94	4.37	4.01	3.55	0.38	19
			P100	25.90	10.45	9.25	8.49	7.52	6.89	6.10	0.57	26
	150	MCV50	P125	38.94	15.96	14.13	12.96	11.48	10.53		0.78	35
	150	IVICVSU	P150	58.35	23.50	20.81	19.09	16.90	15.50		1.16	40
			P175	91.50	37.85	33.52	30.74	27.22	24.97		1.61	45
			P225	202.31	95.61	90.28	82.43	72.70			3.61	60
			P250	261.14	108.23	95.83	87.91	77.84			4.08	70
			P320	555.74	228.79	202.59	185.84				8.42	80
			P050	3.68	1.30	1.15	1.06	0.93	0.86	0.76	0.13	14
			P065	7.81	2.98	2.64	2.42	2.14	1.97	1.74	0.26	16
			P080	15.06	5.75	5.09	4.67	4.14	3.79	3.36	0.41	19
			P100	25.90	9.78	8.66	7.94	7.03	6.45	5.71	0.61	26
		MS	P125	38.94	15.11	13.38	12.27	10.87	9.97	8.83	0.84	35
		1013	P150	58.35	22.25	19.70	18.07	16.00	14.68	13.00	1.24	40
			P175	91.50	35.84	31.73	29.11	25.77	23.64		1.72	45
			P225	202.31	90.21	85.14	79.35	67.93	60.25		3.74	60
			P250	261.14	102.47	90.73	83.23	73.69	67.60		4.32	70
2	180		P320	555.74	216.61	191.80	175.94	155.79			8.88	80
-	100		P050	4.20	1.58	1.40	1.28	1.14	1.04	0.92	0.11	14
			P065	11.00	4.59	4.06	3.73	3.30	3.03	2.68	0.22	16
			P080	17.22	6.99	6.19	5.68	5.03	4.61	4.08	0.34	19
			P100	34.14	15.00	13.28	12.18	10.79	9.89	8.76	0.52	26
		MCV50	P125	55.05	24.39	21.59	19.81	17.54	16.09	14.24	0.73	35
			P150	90.00	39.87	35.30	32.39	28.68	26.30	23.29	1.09	40
			P175	123.27	53.32	47.22	43.31	38.35	35.18		1.50	45
			P225	325.69	154.21	140.93	132.01	112.45	103.21		3.51	60
			P250	387.70	166.44	147.37	135.19	119.70	109.81		3.89	70
			P320	680.19	292.01	258.56	237.18	210.02			7.79	80
			P050	3.89	1.35	1.19	1.09	0.97	0.89	0.78	0.12	14
			P065	8.24	3.07	2.72	2.50	2.21	2.03	1.79	0.24	16
			P080	16.14	6.07	5.37	4.93	4.36	4.00	3.54	0.38	19
			P100	25.90	9.33	8.26	7.58	6.71	6.16	5.45	0.56	26
	210	MS	P125	40.71	15.38	13.62	12.49	11.06	10.15	8.98	0.77	35
			P150	58.35	21.25	18.81	17.26	15.28	14.02	12.41	1.15	40
			P175	91.50	34.22	30.30	27.79	24.61	22.57	19.99	1.60	45
			P225	202.31	85.62	81.43	72.58	64.32	59.91		3.85	60
			P250	261.14	97.83	86.63	79.47	70.36	64.54		4.05	70
			P320	555.74	206.82	183.14	167.99	148.75	136.45		8.37	80



No. of	Indexing			Static Torque		Dyr	namic Torq	jue (kgf-n	n)		Friction Torque	Bearing Dia.	
Stops	Angle	Curve	Model	Ts		Indexing	g Rotating	Speed N	(rpm)			D.G.	
S	θ			(kgf-m)	50	75	100	150	200	300			
			P050	4.73	1.81	1.60	1.47	1.30	1.19	1.06	0.10	14	
			P065	12.80	5.47	4.84	4.44	3.93	3.61	3.19	0.20	16	
			P080	18.83	7.65	6.78	6.22	5.50	5.05	4.47	0.32	19	
			P100	34.14	14.32	12.68	11.63	10.30	9.45	8.36	0.48	26	
	240	1401/50	P125	55.05	23.28	20.62	18.91	16.75	15.36	13.60	0.68	35	
	210	MCV50	P150	90.00	38.07	33.71	30.92	27.38	25.12	22.24	1.03	40	
			P175	123.27	50.91	45.08	41.35	36.62	33.59	29.74	1.41	45	
			P225	345.81	143.60	126.51	117.84	109.61	98.69		3.01	60	
			P250	387.70	158.92	140.71	129.08	114.29	104.84		3.70	70	
			P320	680.19	278.81	246.88	226.46	200.52			7.41	80	
			P050	4.20	1.45	1.28	1.18	1.04	0.96	0.85	0.11	14	
			P065	11.00	4.21	3.73	3.42	3.03	2.78	2.46	0.23	16	
			P080	17.22	6.41	5.68	5.21	4.61	4.23	3.74	0.35	19	
			P100	34.14	13.76	12.18	11.17	9.89	9.07	8.03	0.53	26	
		MS	P125	55.05	22.37	19.81	18.17	16.09	14.76	13.07	0.74	35	
			P150	90.00	36.57	32.39	29.71	26.30	24.13	21.36	1.11	40	
			P175	123.27	48.91	43.31	39.73	35.18	32.27	28.57	1.52	45	
			P225	345.81	140.51	127.90	118.69	107.51	94.32	83.08	3.18	60	
			P250	387.70	152.67	135.19	124.10	109.81	100.73	89.19	3.94	70	
2	240		P320	680.19	267.86	237.18	217.57	192.65	176.72		7.87	80	
	240		P050	4.73	1.74	1.54	1.41	1.25	1.15	1.01	0.09	14	
			P065	11.00	5.25	4.65	4.27	3.78	3.46	3.07	0.19	16	
				P080	19.91	8.03	7.11	6.52	5.77	5.29	4.69	0.30	19
			P100	38.41	16.49	14.60	13.39	11.86	10.87	9.63	0.45	26	
		MCV50	P125	61.66	26.62	23.57	21.62	19.14	17.56	15.55	0.63	35	
		1010030	P150	101.25	43.88	38.81	35.60	31.52	28.91	25.60	0.96	40	
			P175	132.08	54.32	48.10	44.12	39.07	35.84	31.73	1.33	45	
			P225	398.95	165.91	158.12	136.91	120.51	109.43		3.10	60	
			P250	426.47	176.61	156.38	143.45	127.02	116.52		3.47	70	
			P320	743.96	307.12	271.94	249.46	220.89	202.62		7.00	80	
			P050	4.20	1.40	1.24	1.14	1.01	0.92	0.82	0.11	14	
			P065	11.00	4.06	3.60	3.30	2.92	2.68	2.37	0.21	16	
			P080	17.22	6.19	5.48	5.03	4.45	4.08	3.61	0.33	19	
			P100	34.14	13.28	11.76	10.79	9.55	8.76	7.76	0.50	26	
	270	MS	P125	55.05	21.59	19.12	17.54	15.53	14.24	12.61	0.70	35	
			P150	90.00	35.30	31.26	28.68	25.39	23.29	20.62	1.06	40	
			P175	132.08	52.44	46.43	42.59	37.71	34.59	30.63	1.43	45	
			P225	345.81	138.65	127.51	114.32	102.69	95.12	84.05	3.02	60	
			P250	387.70	147.37	130.49	119.70	105.99	97.23	86.09	3.78	70	
			P320	680.19	258.56	228.95	210.02	185.96	170.58		7.57	80	



No. of	Indexing			Static Torque		Dyr	namic Torc	que (kgf-r	n)		Friction Torque	Bearing Dia.
Stops	Angle	Curve	Model	Ts		Indexin	g Rotating	Speed N	(rpm)			Dia.
S	θ			(kgf-m)	50	75	100	150	200	300		
			P050	4.73	1.68	1.49	1.36	1.21	1.11	0.98	0.09	14
			P065	11.00	5.07	4.49	4.12	3.65	3.34	2.96	0.18	16
			P080	19.91	7.75	6.86	6.29	5.57	5.11	4.52	0.28	19
			P100	38.41	15.91	14.09	12.92	11.44	10.50	9.29	0.43	26
			P125	61.66	26.69	22.75	20.87	18.48	16.95	15.01	0.61	35
	270	MCV50	P150	101.25	42.31	37.46	34.36	30.43	27.91	24.71	0.92	40
			P175	140.88	58.00	51.36	47.11	41.72	38.27	33.88	1.26	45
			P225	345.81	163.21	145.51	131.88	118.40	107.69		2.89	60
			P250	426.47	170.48	150.95	138.47	122.61	112.47		3.36	70
			P320	770.53	313.22	277.35	254.41	225.28	206.65		6.73	80
			P050	4.73	1.63	1.44	1.32	1.17	1.07	0.95	0.10	14
			P065	11.00	4.91	4.35	3.99	3.53	3.24	2.87	0.20	16
			P080	19.91	7.51	6.65	6.10	5.40	4.95	4.38	0.31	19
			P100	38.41	15.42	13.65	12.52	11.09	10.17	9.01	0.47	26
2		MS	P125	61.66	24.89	22.04	20.22	17.90	16.42	14.54	0.66	35
	MS	IVIS	P150	101.25	40.99	36.29	33.29	29.48	27.04	23.94	0.99	40
			P175	140.88	56.20	49.76	45.65	40.42	37.08	32.83	1.36	45
			P225	345.81	158.42	140.61	128.65	115.02	104.32	92.60	3.02	60
			P250	426.47	165.18	146.26	134.16	118.80	108.97	96.49	3.58	70
	300		P320	770.53	303.48	268.72	246.50	218.27	200.22		7.15	80
	300		P050	5.25	1.93	1.71	1.56	1.38	1.27	1.12	0.09	14
			P065	11.00	5.59	4.95	4.54	4.02	3.69	3.27	0.17	16
			P080	21.52	8.52	7.54	6.92	6.13	5.62	4.97	0.27	19
			P100	40.00	18.27	16.18	14.84	13.14	12.05	10.67	0.41	26
		MCV50	P125	65.00	27.79	24.61	22.57	19.99	18.33	16.23	0.58	35
		IVICVO	P150	111.00	47.52	42.07	38.59	34.17	31.35	27.76	0.87	40
			P175	154.09	64.97	57.52	52.77	46.72	42.86	37.95	1.20	45
			P225	345.81	173.81	162.14	146.51	133.20	126.51		2.65	60
			P250	484.63	202.77	179.55	164.70	145.84	133.78		3.15	70
			P320	850.24	355.75	315.00	288.96	255.86	234.71		6.40	80
			P050	3.99	2.14	1.90	1.74	1.54	1.41	1.25	0.12	14
			P065	10.24	5.94	5.26	4.82	4.27	3.92	3.47	0.24	19
			P080	16.14	9.23	8.17	7.50	6.64	6.09	5.39	0.37	22
			P100	31.58	19.04	16.86	15.46	13.69	12.56	11.12	0.56	30
3	120	MCV25	P125	51.09	30.84	27.31	25.05	22.18	20.34	18.01	0.79	35
			P150	83.25	49.82	44.11	40.46	35.83	32.87	29.10	1.18	40
			P175	114.47	75.76	67.08	61.54	54.49	49.98	44.26	1.61	50
			P225	245.39	136.74	128.05	104.31	98.75	94.32		3.24	60
			P250	276.07	158.22	140.10	128.52	113.80	104.39		3.99	80
		P320	595.44	342.98	303.70	278.59	246.68			8.23	100	



No. of	Indexing			Static Torque		Dyr	namic Torq	jue ( <b>kgf-</b> n	n)		Friction Torque	Bearing Dia.
Stops	Angle	Curve	Model	Ts (kaf m)		Indexin	g Rotating	Speed N	(rpm)		,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	
S	θ			(kgf-m)	50	75	100	150	200	300		
			P050	4.20	2.15	1.91	1.75	1.55	1.42	1.26	0.12	14
			P065	11.00	6.21	5.49	5.04	4.46	4.09	3.62	0.23	19
			P080	17.22	9.44	8.36	7.67	6.79	6.23	5.51	0.36	22
			P100	34.14	19.84	17.56	16.11	14.26	13.09	11.59	0.54	30
	150	MS	P125	56.15	32.89	29.12	26.71	23.65	21.70	19.21	0.76	35
	150	IVIS	P150	90.00	51.90	45.96	42.16	37.33	34.24	30.32	1.14	40
			P175	123.27	78.51	69.52	63.77	56.47	51.80	45.87	1.56	50
			P225	345.61	204.51	176.35	161.20	137.04	118.65	107.66	3.51	60
			P250	387.70	221.86	196.45	180.20	159.56	146.37	129.61	4.03	80
			P320	680.19	389.24	344.66	316.16	279.95	256.80		8.05	100
			P050	4.73	2.41	2.13	1.96	1.73	1.59	1.41	0.10	14
			P065	11.00	6.52	5.78	5.30	4.69	4.30	3.81	0.21	19
			P080	19.37	10.57	9.36	8.58	7.60	6.97	6.17	0.33	22
			P100	36.70	20.80	18.42	16.89	14.96	13.72	12.15	0.49	30
	180	MS	P125	60.56	34.66	30.69	28.16	24.93	22.87	20.25	0.69	35
	180	1013	P150	101.25	58.09	51.44	47.18	41.78	38.33	33.94	1.03	45
			P175	137.36	86.68	76.75	70.40	62.34	57.18	50.63	1.42	50
			P225	385.64	226.30	198.66	174.31	150.69	141.25		3.16	60
			P250	426.47	240.42	212.88	195.28	172.91	158.62		3.70	80
3			P320	743.96	418.37	370.45	339.82	300.90	276.02		7.44	100
3			P050	4.73	2.30	2.04	1.87	1.65	1.52	1.34	0.10	14
			P065	11.00	6.23	5.52	5.06	4.48	4.11	3.64	0.20	19
			P080	19.37	10.09	8.94	8.20	7.26	6.66	5.89	0.30	22
			P100	40.00	23.28	20.62	18.91	16.74	15.36	13.60	0.45	30
	210	MS	P125	64.41	36.18	32.04	29.39	26.02	23.87	21.14	0.64	35
	210	1013	P150	105.00	58.47	51.77	47.49	42.05	38.57	34.15	0.97	45
			P175	145.28	89.76	79.48	72.91	64.56	59.22	52.44	1.32	50
			P225	408.61	245.31	212.60	198.60	174.25	163.51	140.89	3.02	60
			P250	465.24	260.41	230.59	211.52	187.30	171.81	152.13	3.45	80
			P320	797.10	441.33	390.78	358.47	317.41	291.17		6.99	100
			P050	5.25	2.58	2.28	2.09	1.85	1.70	1.50	0.09	14
			P065	11.00	7.43	6.58	6.04	5.34	4.90	4.34	0.18	19
			P080	21.52	11.31	10.01	9.18	8.13	7.46	6.60	0.28	22
			P100	40.00	23.75	21.03	19.29	17.08	15.67	13.87	0.43	30
	240	MS	P125	65.00	36.07	31.94	29.30	25.94	23.80	21.07	0.61	35
	240	1012	P150	111.00	60.93	53.95	49.49	43.82	40.20	35.60	0.91	45
			P175	154.09	94.02	83.25	76.37	67.62	62.03	54.92	1.25	50
			P225	408.61	235.65	202.63	189.51	163.20	158.47	139.62	2.86	60
			P250	465.24	250.19	221.53	203.22	179.94	165.06	146.16	3.31	80
			P320	797.10	424.00	375.44	344.39	304.95	279.73	247.69	6.73	100



No. of	Indexing			Static Torque		Dyr	namic Torc	que ( <b>kgf-</b> r	n)		Friction Torque	Bearing Dia.
Stops	Angle	Curve	Model	Ts		Indexin	g Rotating	Speed N	(rpm)			S.a.
S	θ			(kgf-m)	50	75	100	150	200	300		
			P050	5.25	2.49	2.20	2.02	1.79	1.64	1.45	0.09	14
			P065	11.00	7.17	6.35	5.83	5.16	4.73	4.19	0.17	19
			P080	21.52	10.92	9.67	8.87	7.85	7.20	6.38	0.27	22
			P100	40.00	22.93	20.30	18.62	16.49	15.13	13.39	0.41	30
	270	MS	P125	65.00	34.82	30.83	28.28	25.04	22.97	20.34	0.58	35
	270	IVIS	P150	111.00	58.82	52.08	47.77	42.30	38.80	34.36	0.88	45
			P175	154.09	90.76	80.36	73.72	65.27	59.87	53.02	1.20	50
			P225	423.74	241.34	208.52	194.32	170.50	162.31	142.54	2.73	60
			P250	484.63	256.45	227.07	208.30	184.44	169.19	149.81	3.17	80
3			P320	850.24	449.92	398.39	365.45	323.59	296.83	262.84	6.43	100
3			P050	5.25	2.41	2.14	1.96	1.73	1.59	1.41	0.08	14
			P065	11.00	6.95	6.15	5.65	5.00	4.58	4.06	0.17	19
			P080	21.52	10.58	9.36	8.59	7.61	6.98	6.18	0.26	22
			P100	40.00	22.22	19.67	18.04	15.98	14.66	12.98	0.39	30
	300 MS	P125	65.00	33.74	29.87	27.40	24.26	22.26	19.71	0.56	35	
		1013	P150	111.00	56.99	50.46	46.29	40.99	37.60	33.29	0.85	45
			P175	154.09	87.93	77.86	71.42	63.24	58.01	51.37	1.17	50
			P225	423.74	238.60	202.41	187.65	163.61	157.84	137.21	2.46	60
			P250	484.63	248.47	220.01	201.82	178.70	163.93	145.15	3.08	80
			P320	850.24	435.92	385.99	354.08	313.52	287.60	254.66	6.27	100
			P050	3.68	2.05	1.81	1.66	1.47	1.35	1.19	0.13	14
			P065	7.81	4.39	3.89	3.57	3.16	2.90	2.56	0.26	16
			P080	15.06	8.41	7.45	6.83	6.05	5.55	4.91	0.41	19
			P100	25.90	14.09	12.47	11.44	10.13	9.29	8.23	0.61	26
	90	MS	P125	38.94	24.57	21.75	19.95	17.67	16.21	14.35	0.84	35
	50	1413	P150	58.35	36.32	32.16	29.50	26.12	23.96		1.24	45
			P175	91.50	56.95	50.42	46.25	40.96	37.57		1.72	50
			P225	223.65	140.25	132.65	122.01	109.33	104.25		3.74	60
			P250	261.14	164.75	145.88	133.82	118.49	108.70		4.32	80
4			P320	555.74	350.62	310.46	284.79	252.17			8.88	100
1			P050	4.20	1.45	1.29	1.18	1.04	0.96	0.85	0.11	14
			P065	11.00	4.84	4.29	3.93	3.48	3.19	2.83	0.23	16
			P080	17.22	7.36	6.51	5.97	5.29	4.85	4.29	0.35	19
			P100	34.14	16.26	14.40	13.21	11.69	10.72	9.50	0.53	32
	120	MS	P125	55.05	29.61	26.22	24.05	21.30	19.53	17.30	0.74	35
	120	1415	P150	90.00	48.41	42.86	39.32	34.81	31.93	28.28	1.11	45
			P175	123.27	64.44	57.06	52.34	46.34	42.51	37.64	1.52	50
			P225	354.26	178.64	151.20	140.12	128.65	118.45		3.51	60
			P250	387.70	191.31	169.40	155.39	137.59	126.21		3.94	80
			P320	680.19	335.64	297.20	272.62	241.40			7.87	100



No. of	Indexing	0	Martal	Static Torque		Dyr	namic Torq	jue (kgf-r	n)		Friction Torque	Bearing Dia.
Stops S	Angle O	Curve	Model	Ts (kgf-m)		Indexin	g Rotating	Speed N	(rpm)			
5	θ			(kgi-iii)	50	75	100	150	200	300		
			P050	4.73	1.63	1.44	1.32	1.17	1.07	0.95	0.10	14
			P065	11.00	5.65	5.00	4.59	4.06	3.72	3.30	0.20	16
			P080	19.91	8.61	7.62	6.99	6.19	5.68	5.03	0.31	19
			P100	38.41	18.22	16.13	14.80	13.10	12.02	10.64	0.47	30
	150	MS	P125	61.66	29.18	25.84	23.70	20.98	19.25	17.04	0.66	35
	150	1013	P150	101.25	48.03	42.53	39.01	34.55	31.69	28.06	0.99	45
			P175	140.88	65.55	58.04	53.24	47.15	43.25	38.29	1.36	50
			P225	387.65	173.31	156.14	141.33	124.52	113.65		3.14	60
			P250	426.47	183.27	162.28	148.86	131.81	120.91		3.58	80
			P320	743.96	318.69	282.19	258.86	229.21	210.26		7.20	100
			P050	5.25	1.83	1.62	1.48	1.31	1.21	1.07	0.09	14
			P065	11.00	5.58	4.94	4.53	4.01	3.68	3.26	0.18	19
			P080	21.52	8.48	7.51	6.89	6.10	5.60	4.95	0.28	22
			P100	40.00	18.75	16.61	15.23	13.49	12.37	10.95	0.43	30
	180	NAC	P125	65.00	30.84	27.31	25.05	22.18	20.35	18.01	0.61	40
	180	) MS	P150	111.00	52.72	46.68	42.82	37.92	34.78	30.80	0.91	45
			P175	154.09	71.75	63.53	58.27	51.60	47.33	41.91	1.25	50
			P225	453.62	202.56	174.92	162.35	147.99	129.85		2.87	60
			P250	484.63	213.00	188.61	173.01	153.20	140.53		3.27	80
4			P320	850.24	373.70	330.90	303.54	268.77	246.55		6.63	100
4			P050	5.25	1.75	1.55	1.42	1.25	1.15	1.02	0.08	14
			P065	11.00	5.33	4.72	4.33	3.83	3.52	3.11	0.17	19
			P080	21.52	8.10	7.17	6.58	5.83	5.34	4.73	0.27	22
			P100	40.00	17.91	15.85	14.54	12.88	11.81	10.46	0.40	30
	210	MS	P125	65.00	29.45	26.07	23.92	21.18	19.43	17.20	0.58	40
	210	1013	P150	111.00	50.34	44.57	40.89	36.20	33.21	29.40	0.87	45
			P175	154.09	68.50	60.66	55.64	49.27	45.19	40.02	1.19	50
			P225	453.62	195.43	168.52	156.94	143.21	128.50	112.32	2.62	60
			P250	484.63	203.38	180.08	165.19	146.27	134.18	118.81	3.14	80
			P320	850.24	356.81	315.95	289.82	256.63	235.41		6.37	100
			P050	5.25	1.68	1.48	1.36	1.21	1.11	0.98	0.08	14
			P065	11.00	5.12	4.53	4.16	3.68	3.38	2.99	0.16	19
			P080	21.52	7.78	6.89	6.32	5.60	5.13	4.54	0.25	22
			P100	40.00	17.20	15.23	13.97	12.37	11.35	10.05	0.39	30
	240	MS	P125	65.00	28.29	25.05	22.98	20.35	18.66	16.52	0.55	40
	240	IVIS	P150	111.00	48.36	42.82	39.28	34.78	31.90	28.25	0.83	45
			P175	154.09	65.81	58.27	53.46	47.33	43.42	38.45	1.14	50
			P225	453.62	190.32	160.21	150.31	138.25	120.34	108.75	2.58	60
			P250	484.63	195.39	173.01	158.71	140.53	128.91	114.14	3.04	80
	<u> </u>		P320	850.24	342.80	303.54	278.44	246.55	226.16		6.18	100



No. of	Indexing			Static Torque		Dyr	namic Torc	que ( <b>kgf-</b> r	n)		Friction Torque	Bearing Dia.
Stops	Angle	Curve	Model	Ts		Indexin	g Rotating	Speed N	(rpm)		Torque	Dia.
S	θ			(kgf-m)	50	75	100	150	200	300		
			P050	5.25	1.62	1.43	1.31	1.16	1.07	0.94	0.08	14
			P065	11.00	4.94	4.38	4.01	3.55	3.26	2.89	0.16	19
			P080	21.52	7.51	6.65	6.10	5.40	4.95	4.39	0.25	22
			P100	40.00	16.61	14.70	13.49	11.94	10.95	9.70	0.37	30
	270		P125	65.00	27.31	24.18	22.18	19.64	18.01	15.95	0.53	40
	270	MS	P150	111.00	46.68	41.33	37.92	33.57	30.80	27.27	0.81	45
			P175	154.09	63.53	56.25	51.60	45.69	41.91	37.11	1.11	50
			P225	453.62	183.40	161.25	146.31	128.65	116.51	104.32	2.31	60
			P250	484.63	188.61	167.00	153.20	135.65	124.43	110.18	2.96	80
4			P320	850.24	330.90	293.00	268.77	237.99	218.31	193.31	6.02	100
4			P050	5.25	1.57	1.39	1.27	1.13	1.03	0.91	0.07	14
			P065	11.00	4.79	4.24	3.89	3.44	3.16	2.80	0.15	19
			P080	21.52	7.28	6.44	5.91	5.23	4.80	4.25	0.24	22
			P100	40.00	16.09	14.25	13.07		10.61	9.40	0.36	30
	200	NAC	P125	65.00	26.46	23.43	21.49	19.03	17.45	15.45	0.52	40
	300	300 MS	P150	111.00	45.23	40.05	36.74		29.84	26.42	0.79	45
			P175	154.09	61.55	54.50	49.99	44.27	40.61	35.96	1.08	50
			P225	453.62	178.51	156.82	140.33	124.83	112.37	102.50	2.31	60
			P250	484.63	182.74	161.81	148.43	131.43	120.56	106.75	2.90	80
			P320	850.24	320.61	283.89	260.41		211.52	187.29	5.90	100
			P050	4.20	1.78	1.57	1.44	1.28	1.17	1.04	0.11	14
			P065	11.00	6.57	5.81	5.33		4.33	3.83	0.21	19
			P080	17.22	10.12	8.96	8.22	7.28	6.68	5.91	0.32	19
			P100	31.58	19.02	16.84	15.44		12.54	11.11	0.49	30
	180	MS	P125	56.15	34.84	30.84	28.29	25.05	22.98	20.35	0.66	35
	180	IVIS	P150	93.00	58.97	52.22	47.90		38.91	34.45	0.97	40
			P175	129.43	79.98	70.82	64.97	57.52	52.77	46.72	1.29	45
			P225	245.39	139.86	130.21	106.51	101.25	96.38		2.84	60
			P250	276.07	161.08	142.63	130.84	115.85	106.27		3.06	80
6			P320	595.44	349.19	309.19	283.63		230.37		6.00	100
			P050	4.73	2.01	1.78	1.63	1.44	1.32	1.17	0.10	14
			P065	11.00	6.96	6.16	5.65		4.59	4.06	0.20	19
			P080	19.37	11.43	10.12	9.28	8.22	7.54	6.67	0.30	19
			P100	36.70	22.40	19.83	18.19		14.78	13.08	0.45	30
	210 MS	MS	P125	60.56	37.03	32.79	30.07	26.63	24.43	21.63	0.61	35
			P150	101.25	63.57	56.29	51.63		41.94	37.14	0.89	40
			P175	137.36	83.13	73.61	67.52	59.79	54.85	48.56	1.19	45
			P225	354.26	212.01	193.21	167.25	152.01	142.51	130.20	2.76	60
			P250	387.70	231.66	205.13	188.16	166.61	152.84	135.33	3.00	80
			P320	678.43	406.43	359.88	330.12	292.31	268.14		5.62	100



No. of	Indexing			Static Torque		Dyr	namic Torq	jue (kgf-r	n)		Friction Torque	Bearing Dia.
Stops	Angle	Curve	Model	Ts		Indexin	g Rotating	Speed N	(rpm)		101940	Dia.
S	θ			(kgf-m)	50	75	100	150	200	300		
			P050	5.25	2.25	1.99	1.83	1.62	1.48	1.31	0.09	14
			P065	13.21	7.39	6.54	6.00	5.31	4.87	4.31	0.19	19
			P080	20.44	11.88	10.51	9.65	8.54	7.83	6.94	0.28	19
			P100	34.51	25.23	22.34	20.49	18.15	16.65	14.74	0.41	30
	2.40		P125	64.41	38.89	34.44	31.59	27.97	25.66	22.72	0.57	35
	240	MS	P150	112.63	64.38	57.00	52.29	46.30	42.47	37.61	0.84	40
			P175	145.28	86.63	76.71	70.37	62.31	57.15	50.61	1.12	45
			P225	432.65	262.31	241.86	226.15	201.35	182.31	162.87	2.33	60
			P250	465.24	288.99	255.89	234.73	207.85	190.66	168.82	2.71	80
_			P320	723.65	489.75	433.66	397.80	352.24	323.11		5.13	100
6			P050	5.25	2.17	1.92	1.76	1.56	1.43	1.27	0.09	14
			P065	14.05	8.02	7.10	6.51	5.77	5.29	4.68	0.17	19
			P080	21.52	12.36	10.94	10.04	8.89	8.15	7.22	0.26	19
			P100	35.62	25.86	22.90	21.01	18.60	17.06	15.11	0.39	30
	270 MS	MC	P125	65.00	38.95	34.49	31.64	28.02	25.70	22.75	0.54	35
		WIS	P150	114.82	67.41	59.69	54.75	48.48	44.47	39.38	0.79	40
			P175	154.09	91.17	80.72	74.05	65.57	60.15	53.26	1.05	45
			P225	546.72	270.31	248.65	231.25	213.01	187.65	168.19	2.21	60
			P250	584.63	296.22	262.29	240.60	213.04	195.43	173.04	2.57	80
			P320	831.69	519.69	460.17	422.12	373.77	342.87		4.83	100
			P050	3.68	1.67	1.48	1.36	1.20	1.10	0.97	0.11	14
			P065	11.00	4.32	3.82	3.51	3.10	2.85	2.52	0.23	16
			P080	15.06	8.27	7.32	6.72	5.95	5.45	4.83	0.35	19
			P100	25.90	13.94	12.34	11.32	10.02	9.19	8.14	0.51	26
	120	MS	P125	38.94	21.01	18.60	17.06	15.11	13.86	12.27	0.69	30
	120	1113	P150	58.35	31.75	28.11	25.79	22.83	20.94		0.99	40
			P175	91.50	49.50	43.83	40.20	35.60	32.65		1.36	45
			P225	223.65	128.65	117.36	108.42	96.51			2.91	60
			P250	261.14	141.50	125.29	114.93	101.77			3.25	80
8			P320	555.74	301.13	266.64	244.59	216.58			6.38	100
			P050	3.89	1.37	1.22	1.12	0.99	0.90	0.80	0.10	14
			P065	8.24	3.54	3.14	2.88	2.55	2.34	2.07	0.20	16
			P080	17.22	7.63	6.76	6.20	5.49	5.03	4.46	0.31	19
			P100	34.14	16.39	14.52	13.32	11.79	10.81	9.58	0.46	26
	150	MS	P125	55.05	26.44	23.41	21.47	19.01	17.44	15.44	0.63	30
			P150	90.00	44.04	39.00	35.77	31.68	29.06	25.73	0.93	40
			P175	123.27	60.33	53.42	49.00	43.39	39.80		1.24	45
			P225	354.26	146.37	132.21	122.69	108.95	97.61		2.61	60
			P250	387.70	169.67	150.24	137.81	122.03	111.94		3.05	80
			P320	680.19	321.00	284.23	260.73	230.87			5.73	100



No. of	Indexing			Static Torque		Dyr	namic Torc	ղսе ( <b>kgf-</b> r	n)		Friction Torque	Bearing Dia.
Stops	Angle	Curve	Model	Ts (kgf m)		Indexin	g Rotating	Speed N	(rpm)			Bid.
S	θ			(kgf-m)	50	75	100	150	200	300		
			P050	4.20	1.46	1.29	1.18	1.05	0.96	0.85	0.09	14
			P065	11.00	4.76	4.21	3.86	3.42	3.14	2.78	0.19	19
			P080	19.91	9.04	8.01	7.35	6.50	5.97	5.28	0.28	22
			P100	38.41	18.60	16.47	15.11	13.38	12.27	10.86	0.42	26
	100	N.4.C	P125	61.66	29.79	26.37	24.19	21.42	19.65	17.40	0.58	30
	180	MS	P150	101.25	49.97	44.24	40.59	35.94	32.96	29.19	0.84	40
			P175	137.36	67.42	59.70	54.76	48.49	44.48	39.38	1.13	45
			P225	386.52	184.65	161.30	147.32	136.51	126.51		2.05	60
			P250	426.47	200.38	177.43	162.76	144.12	132.20		2.79	80
			P320	743.96	348.46	308.55	283.03	250.62			5.24	100
			P050	4.73	1.67	1.48	1.36	1.20	1.10	0.97	0.09	14
			P065	11.00	5.08	4.50	4.13	3.65	3.35	2.97	0.18	19
			P080	19.91	8.64	7.65	7.01	6.21	5.70	5.04	0.26	22
			P100	38.41	17.76	15.72	14.42	12.77	11.72	10.37	0.40	26
	210	NAC	P125	61.66	28.44	25.18	23.10	20.45	18.76	16.61	0.54	30
	210	MS	P150	101.25	47.71	42.24	38.75	34.31	31.47	27.87	0.80	40
			P175	140.88	66.99	59.32	54.42	48.18	44.20	39.14	1.07	45
			P225	386.52	178.65	157.31	143.25	130.20	120.51		1.94	60
			P250	426.47	191.33	169.41	155.41	137.61	126.23		2.65	80
			P320	770.53	351.52	311.26	285.52	252.82	231.92		4.93	100
8			P050	5.25	1.90	1.68	1.54	1.37	1.25	1.11	0.08	14
			P065	11.00	6.20	5.49	5.03	4.46	4.09	3.62	0.16	19
			P080	21.52	9.42	8.34	7.65	6.77	6.21	5.50	0.25	22
			P100	40.00	20.22	17.90	16.42	14.54	13.34	11.81	0.37	26
	240	MS	P125	65.00	30.50	27.01	24.78	21.94	20.12	17.82	0.51	30
	240	1013	P150	111.00	53.14	47.05	43.16	38.21	35.05	31.04	0.75	40
			P175	154.09	74.40	65.88	60.43	53.51	49.09	43.46	1.00	45
			P225	420.63	203.60	187.41	171.25	150.65	132.05		1.72	60
			P250	484.63	225.65	199.81	183.28	162.29	148.87		2.44	80
			P320	850.24	395.89	350.55	321.56	284.73	261.19		4.58	100
			P050	5.25	1.84	1.63	1.49	1.32	1.21	1.07	0.08	14
			P065	11.00	5.98	5.30	4.86	4.30	3.94	3.49	0.16	19
			P080	21.52	9.09	8.05	7.38	6.54	5.99	5.31	0.24	22
			P100	40.00	19.52	17.28	15.85	14.04	12.88	11.40	0.36	26
	270	MS	P125	65.00	29.44	26.07	23.91	21.18	19.42	17.20	0.49	30
	2/0	1913	P150	111.00	51.29	45.42	41.66	36.89	33.84	29.96	0.72	40
			P175	154.09	71.82	63.59	58.34	51.65	47.38	41.96	0.96	45
			P225	420.63	196.31	180.25	162.31	142.50	127.86	112.01	1.68	60
			P250	484.63	217.82	192.87	176.92	156.66	143.70	127.24	2.36	80
			P320	850.24	382.15	338.38	310.40	274.85	252.12		4.42	100





The reference value of the safe load Fe is:

When the indexing angle is 90  $^{\circ}$ , the safety factor = load torque (Tt) X2.22 (times) When the indexing angle is 120  $^{\circ}$  or above, the safety factor = load torque (Tt) x2.0 (times) Note: For safety factor calculation, when the input shaft speed is lower than 35rpm, it will be considered as 35rpm.



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